



Escola de Camins
Escola Tècnica Superior d'Enginyeria de Camins, Canals i Ports
UPC BARCELONATECH

FINAL DISSERTATION

Title

**Modelling of hydrocarbons dispersion.
Adaptation and improvement of a state
of the art model**

Author

Paula Martín Laguna

Tutor

Agustín Sánchez-Arcilla Conejo and Marc Mestres Ridge

Department

Ingeniería marítima

Intensification

Modelización

Date

September 2016

Coastal waters quality is a big concern in our society. It is necessary to assure the parameters of the big ecosystem which is the sea are as invariable as possible so the life in it progresses and does not decrease. For this purpose, it is necessary to own tools in case a spill happens so the authorities can quickly design an action plan. There are several models which simulate the dispersion of hydrocarbons in the sea but few of them do it following both Lagrange and Stokes dispersion and movement theories. MEDSLIK_II is one of them but until now it was only able to process one certain type of input data. This dissertation brings a modification of the software so it is able a widely used type of currents and sea temperature forecast data: ROMS. After understanding the theory behind MEDSLIK_II, a new subroutine has been coded so the software becomes more universal.

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1. Introduction

The quality of the sea is currently a big concern to our society. Climate change together with uncontrolled spills from factories and cities' sewages threat everyday our coastal waters. Moreover, it is also important to take into account the oil pipes and overseas oil platforms, which need to follow high standards to ensure they do not compromise the quality of the water.

However, although governments are keeping a close eye on it and are continuously developing new strategies and policies, it is still necessary to own tools which help in case of a disaster, such as accidental leakages or spills.

Numerical modelling is a powerful tool in these cases. It allows us to work with a huge amount of data in a, relatively, small amount of time. The simulations performed by these models are an important source of information for the actions plans.

There are currently several models which have been develop in order to predict how a leak will disperse across the surface and the water column. Special attention is given to hydrocarbons leakages since they are a huge pollution source. The theory behind the simulation is usually either Lagrange, Stokes or a combination of both of them. The main inputs in every case are, on the one hand, sea variables such as currents speed, sea surface temperature and bathymetry; and, on the other, information about the leak such as type of oil and initial location. The sea data comes from different programs which extract it from boys located in the sea and process it. There are many sea data sources around the world but, unluckily, they do not generated files with the same structure. This generates problems when trying to standardize the dispersion of hydrocarbons modelling.

This dissertation has its initial point in an already existing free software called MEDSLIK II, developed originally by Robin Lardner and George Zodiatis and later modified by Michaela De Dominicis. This program can simulate oil dispersion across the entire Mediterranean Sea, allowing the user to reduce the sea section to work with by dividing it in different areas. MEDSLIK II combines both Lagrange and Stokes theories when simulating the movement of the oil particles. This document contains a chapter which goes through the theory behind the modelling process.

Even though MEDSLIK II is prepared to model any part of the Mediterranean Sea, it cannot be used in certain areas because the sea data locally obtained, ROMS data, does not match the data MEDSLIK II is prepared for. As said before, it is necessary and positive to own the more standardized tools possible so they can be used any time anywhere in the world. Therefore, this dissertation aims to upgrade MEDSLIK II so it can also process the sea data coming from ROMS, which is a free-surface, terrain-following, primitive equations ocean model widely used by the scientific community for a diverse range of applications.

2. Objectives and method

Nowadays standardization is key for the globalized society we live in. Any tool or process pursues the final goal of being able to be used anywhere in the world, providing a unique language so professionals can easily communicate and work together no matter where are they from.

Following what stated above, the main target of this dissertation is to provide an upgraded and generic tool which can process ROMS input files to model the dispersion of hydrocarbons in the sea. MEDSLIK II, a free software Fortran 77 based, is going to set the starting point.

To accomplish that, it is necessary to first understand and go through the theory that the base program MEDSLIK II uses to process and work with the data. Secondly, the structure of the code has to be analysed so it is possible to identify where it needs to be modified or added extra programing. Parallel to that, ROMS files are compared to the files that the program currently uses in order to find similarities. Once all these aspects are clear, new code lines will be added to the different sections. The structure of the code does not have to be changed in excess so the computation time does not increase. Finally, the code is compiled so it can be verified using available data for a hypothetical spill.

Special importance is given to the harmony of the code. Free software needs to be clean and clear so any user can easily read and understand it and, ultimately modify it.

3. MEDSLIK_II. Theory background

3.1. Introduction

The aim of this paper is to modify the already existent software MEDSLIK_II, so more sort of input data can be processed, specifically ROMS data. In this section the theory behind the performance of the program is presented. It is really important to understand how the software works so one can identify its needs and apply them when generating new code lines.

MEDSLIK_II simulates the evolution of an oil spill through coastal waters taking into account the meteorological and marine conditions at the air-sea interface (wind, waves and water temperature); the chemical characteristics of the oil; its initial volume and release rates; and the marine currents at different space scales and timescales. All of them are used when simulating the processes which are involved in the transport of contaminant in shallow seas, which are shown in Figure 1.

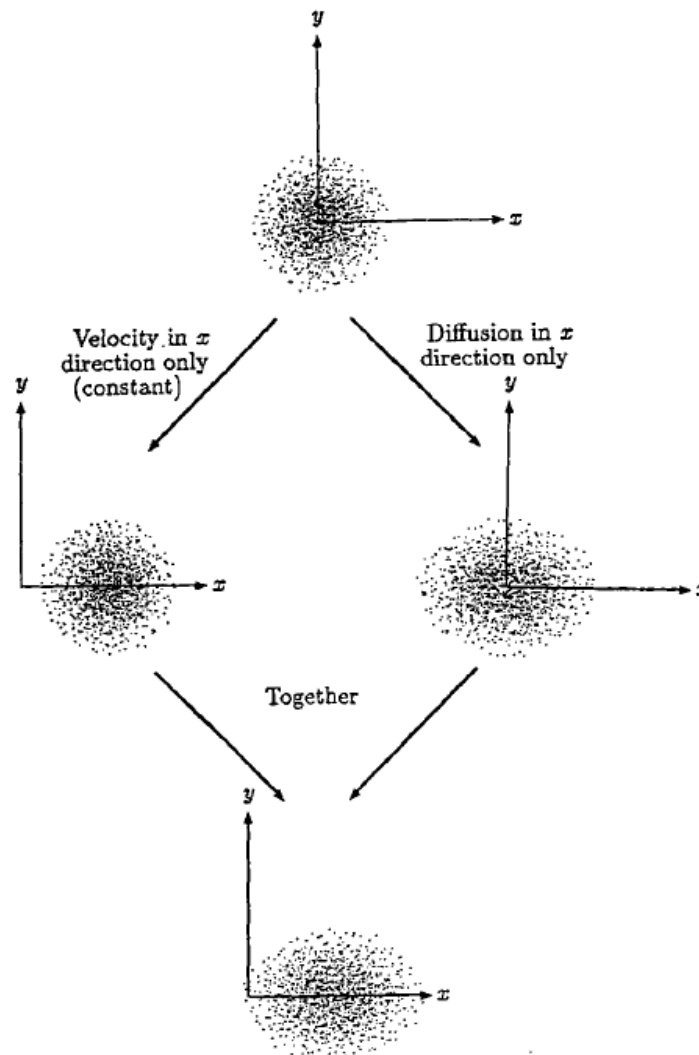


Figure 1: The advective and diffusive processes which are involved in the transport of contaminants in shallow seas (Noye, 1987)

The processes of transport, diffusion and transformation of the surface oil can be simulated with a Lagrangian model formalism coupled with Eulerian circulation models not found adequately described before and which MEDSLIK-II brings. (De Dominicis, et al., 2013)

Eulerian methods are based on the solution of the transport equation described in terms of a fixed coordinate system, while Lagrangian methods use a moving, deformable numerical coordinate system which follows the fluid flow; there is a new variable grid every time step (Noye, 1987). In Eulerian-Lagrangian methods, the advective part of the transport equation is treated in Lagrangian form and the results are usually interpolated onto a fixed (Eulerian) grid. These methods combine the convenience of a Eulerian grid for the solution of the diffusive part of the transport process with the accuracy of a Lagrangian treatment of the advective part.

Thereby, MEDSLIK-II is based on the reconstruction of an oil concentration field from the oil particles advection-diffusion processes. Also, different oil spill state variables are introduced and described. Finally, the model works with the input of recent data sets from numerical oceanographic models.

In this section, the main theory behind MEDSLIK-II is reviewed using M. De Dominicis, et al. (2013) paper as basis. One should refer to the article for the inside calculations related to oil characteristics and dispersions processes.

3.2. Model equations and state variables

As it has been stated in the introduction of this section, the innovation that MEDSLIK-II brings is the connection between the Lagrangian particle approach and the Eulerian oil concentration reconstruction. Equation 1 is the general equation for a tracer concentration, whose numerical solution in a Eulerian context is a well-known problem in oceanographic modelling (Noye, 1987):

$$\frac{\partial C}{\partial t} + U \cdot \nabla C = \nabla \cdot (K \nabla C) + \sum_{j=1}^M r_j(x, C(x, t), t) \quad (1)$$

where C is a tracer concentration, U is the sea current mean field with components (U, V, W) ; K is the diffusivity tensor which parameterizes the turbulent effects and $r_j(C)$ are the M transformation rates that modify the tracer concentration.

Different assumptions are made in order to make the connection possible. First of all, the consideration that the constituent particles do not influence water hydrodynamics and processes. Limitations exist at the water surface, because oil modifies air-sea interactions and surface wind drag. Besides, the constituent particles move with infinitesimal displacements without inertia and without interaction among them. Therefore, the volume of each particle is modified due to the chemical and physical processes acting on the entire slick instead of on every single particle

After considering these assumptions, Equation 1 can be split in Equations 2 and 3:

$$\frac{\partial C_1}{\partial t} = \sum_{j=1}^M r_j(x, C_1(x, t), t) \quad (2)$$

$$\frac{\partial C}{\partial t} = -U \cdot \nabla C_1 + \nabla \cdot (K \nabla C_1) \quad (3)$$

where C_1 is the oil concentration solution only due the weathering processes.

The model first solves Equation 2 by mean of oil slick state variables. Then, the Lagrangian formalism is applied to solve Equation. 3, discretizing the oil slick in particles with associated oil slick state variables. The concentration is obtained assembling the particles together.

MEDSLIK_{II} subdivides the main concentration C into four components, which are called structural state variables.

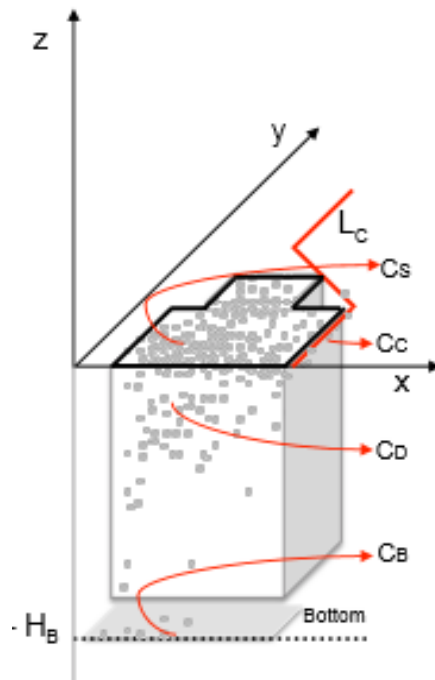


Figure 2: Graphic representation of concentration classes (De Dominicis, et al., 2013)

Below, the different sub-concentrations are introduced:

- C_S , Concentration at the surface. The oil slick is assumed as a continuous layer of material.

$$C_S(x, y, t) = \frac{m}{A} = \frac{\rho}{A} \cdot V_S [kgm^{-2}] \quad (4)$$

where m is the oil weight and A is the unit area.

- C_D , Concentration at the subsurface. Droplets of various sizes form the oil. They can stick to the surface oil slick or sediment at the bottom.

$$C_D(x, y, t) = \frac{\rho}{A} \cdot V_D [kgm^{-2}] \quad (5)$$

- C_C , Concentration adsorbed on the coast. A reference segment, L_C , defines the coast where part of the surface oil gets adsorbed. Its volume has not any prognostic equation and it is calculated from the oil particle state variables, described below.

$$C_C(x, y, t) = \frac{\rho}{L_C} \cdot V_C [kgm^{-2}] \quad (6)$$

where L_C is a referent segment and V_C is the adsorbed oil

- C_B , Concentration on the bottom. It is considered as a sink of oil dispersed in the water column. In the model, it is not computed but represented by a number of oil particles that reach the bottom.

Variable	Variable type	Variable name	Dimensions
$C_S(x, y, t)$	Structural	Oil concentration at the surface	$kg\ m^{-2}$
$C_D(x, y, t)$	Structural	Oil concentration dispersed	$kg\ m^{-2}$
$C_C(x, y, t)$	Structural	Oil concentration on the coast	$kg\ m^{-1}$
$C_B(x, y, t)$	Structural	Oil concentration at the bottom	$kg\ m^{-2}$
$V_S(x, y, t)$	Slick	Oil slick surface volume	m^3
$V_D(x, y, t)$	Slick	Oil slick subsurface (dispersed) volume	m^3
$V^{TK}(x, y, t)$	Slick	Thick part of the surface oil slick volume	m^3
$V^{TN}(x, y, t)$	Slick	Thin part of the surface oil slick volume	m^3
$A^{TK}(t)$	Slick	Surface area of the thick part of the surface oil slick volume	m^2
$A^{TN}(t)$	Slick	Surface area of the thin part of the surface oil slick volume	m^2
$T^{TK}(x, y, t)$	Slick	Surface thickness of the thick part of the surface oil slick volume	m
$T^{TN}(x, y, t)$	Slick	Surface thickness of the thin part of the surface oil slick volume	m
$\mathbf{x}_k(t) = (x_k(t), y_k(t), z_k(t))$	Particle	Particle position	m
$v_{NE}(n_k, t)$	Particle	Non-evaporative surface oil volume particle attribute	m^3
$v_E(n_k, t)$	Particle	Evaporative surface oil volume particle attribute	m^3
$\sigma(n_k, t) = 0, 1, 2, < 0$	Particle	Particle status index (on surface, dispersed, sedimented, on coast)	–

Table 1: Oil spill model state variables (De Dominicis, et al., 2013)

The weathering processes showed in Equation 2 are applied to C_S and C_D , particularly to the oil volumes, which are the basic oil slick variables of the problem. In Table 1 all the variables are summarized.

$$\frac{dC_S}{dt} = \frac{\rho}{A} \frac{dV_S}{dt} \quad (7)$$

$$\frac{dC_D}{dt} = \frac{\rho}{A} \frac{dV_D}{dt} \quad (8)$$

These two equations are the MEDSLIK_II equations for the concentration C_1 in Equation 2. the volumes change following the Mackay et al.(1980) fate algorithms which model the weathering processes. The basis of Mackay's model is to divide the spill into a thick slick and

a thin slick. Evaporation and dispersion are considered separately for these two parts of the slick (Al-Rabeh, et al., 2000).

To solve Equations 7 and 8, the surface volume is subdivided in a thin and a thick part, V^{TN} and V^{TK} . This assumption is made in order to apply Mackay et al (1980) transformation process algorithms. The mentioned volumes are written as follows

$$V^{TN}(x, y, t) = A^{TN}(t)T^{TN}(x, y, t) \quad (9)$$

$$V^{TK}(x, y, t) = A^{TK}(t)T^{TK}(x, y, t) \quad (10)$$

where A^{TK} and A^{TN} are the areas occupied by the thick and thin surface and T^{TK} and T^{TN} are the thicknesses of each surface.

These are oil slick state variables which are used to solve the concentration changes due to weathering processes (see section 3.4).

The surface oil volume is then written as

$$V_S = V^{TN} + V^{TK} \quad (11)$$

On the other hand, to solve the advection-diffusion processes in Equation 3, and compute C_S , C_D and C_C , particle state variables are defined. The surface volume V_S is broken into N constituent particles which are characterized by a particle volume, $\delta(n_k, t)$, a particle status index, $\sigma(n_k, t)$, and a particle position vector:

$$x_k(n_k, t) = (x_k(n_k, t), y_k(n_k, t), z_k(n_k, t)) \quad k = 1, N \quad (12)$$

where n_k is the particle identification number

The evolution of this vector is given by the Langevin equation described in section 3.5.

Following Mackay's conceptual model, the particle volume state variables are subdivided into the evaporative and non-evaporative particle volume attributes:

$$\partial(n_k, t) = \partial_E(n_k, t) + \partial_{NE}(n_k, t) \quad (13)$$

These volumes are updated using empirical formulas that relate them to the time rate of change of oil slick volume state variables, see section 3.4.

The status index identifies the particles corresponding to the four structural state variables: for particles at the surface, $\sigma(n_k, t)=0$; for subsurface or dispersed particles $\sigma(n_k, t)=1$; for sedimented particles, $\sigma(n_k, t)=2$; and for particles on the coasts $\sigma(n_k, t)=-L_i$, where L_i is a coastline segment index, to be specified later.

In order to solve the complete advection-diffusion ad transformation problem in Equation 1, it is necessary to specify a numerical grid where particles can be count and compute the

concentration. Also, it allows defining a solution methodology, since there is no analytical relationship between the oil slick and the particle state variables.

3.3. MEDSLIK-II tracer grid and solution methodology

To connect Equation 2 and Equation 3, a discrete oil tracer grid system is defined, $\mathbf{x}_T=(x_T, y_T)$, with a uniform but different grid spacing in the zonal and meridional directions, $(\delta x_T, \delta y_T)$. Therefore, the spatially discretized time evolution equations for the structural state variables are

$$\frac{dC_S}{dt}(x_T, y_T, t) = \frac{\rho}{\delta x_T \delta y_T} \frac{dV_S}{dt}(x_T, y_T, t) \quad (14)$$

$$\frac{dC_D}{dt}(x_T, y_T, t) = \frac{\rho}{\delta x_T \delta y_T} \frac{dV_D}{dt}(x_T, y_T, t) \quad (15)$$

The coastline is designed as a polygonal chain of points connected by segments of different lengths δL_i , which finally constitute the coastline segment L_i . Following this, Equation 6 becomes

$$C_C(L_i, t) = \frac{\rho}{\delta L_i} \cdot V_C(L_i, t) \quad (16)$$

By relating the particle state variables to the oil tracer grid, it is possible to write the relationship between structural and particle state variables. That means being able to, for instance, follow the evolution of the different concentrations. The countable groups, I_S , I_D , of surface and subsurface particles contained in an oil tracer grid cell are defined as

$$I_S(x_T, y_T, t) = \begin{cases} x_T - \frac{\delta x_T}{2} = x_k(t) = x_T + \frac{\delta x_T}{2} \\ n_k; y_T - \frac{\delta y_T}{2} = y_k(t) = y_T + \frac{\delta y_T}{2} \\ \sigma(n_k, t) = 0 \end{cases} \quad (17)$$

$$I_D(x_T, y_T, t) = \begin{cases} x_T - \frac{\delta x_T}{2} = x_k(t) = x_T + \frac{\delta x_T}{2} \\ n_k; y_T - \frac{\delta y_T}{2} = y_k(t) = y_T + \frac{\delta y_T}{2} \\ \sigma(n_k, t) = 1 \end{cases} \quad (18)$$

Taking into account that, the surface and dispersed concentration can be reconstructed as

$$\begin{cases} C_S(x_T, y_T, t) = \frac{\rho}{\delta x_T \delta y_T} \sum_{n_k \in I_S} \rho(n_k, t) \\ C_D(x_T, y_T, t) = \frac{\rho}{\delta x_T \delta y_T} \sum_{n_k \in I_D} \rho(n_k, t) \end{cases} \quad (19)$$

To calculate the oil concentration on the coast, the set of particles attached to the coastal segment L_i , I_C , is used:

$$I_C(L_i, t) = \{n_k; \sigma(n_k, t) = -L_i\} \quad (20)$$

Then, the concentration of oil on each coastal segment is calculated by

$$C_D(L_i, t) = \frac{\rho}{\delta L_i} \sum_{n_k \in I_D} \rho(n_k, t) \quad (21)$$

In order to solve the different concentrations using the oil slick and particle state variable equation, it is necessary to create a sequential solution. As it is represented in Figure 3 MEDSLIK-II sets the initial conditions and solves the transformation processes (evaporation, dispersion, spreading). After, the thin and thick parts are updated, together with the particles volumes. After, the calculations to relocate the particle positions and update the particle status index are performed. Finally, MEDSLIK-II calculates the oil concentrations as described in Equations 19 and 21.

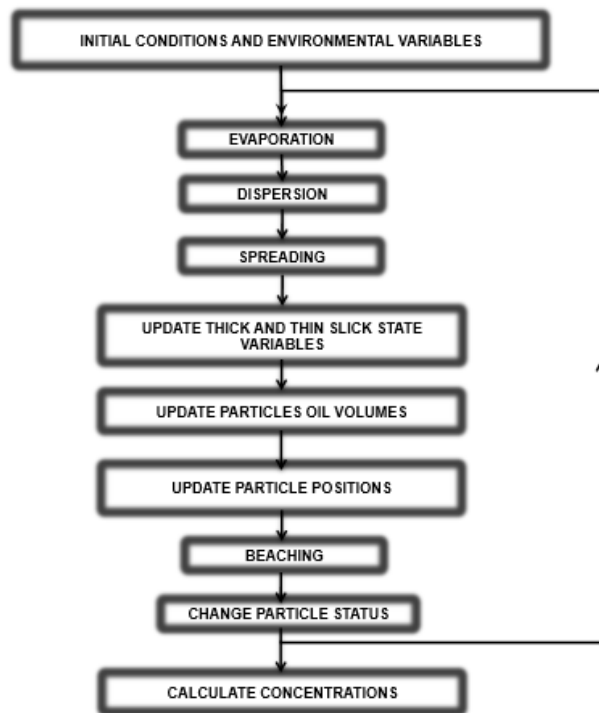


Figure 3: MEDSLIK-II model solution procedure methodology (De Dominicis, et al., 2013)

One of the most significant approximations is that the oil slick state variables depend only on the slick's centre geographical position, which is updated after each advection-diffusion time step. The oil spill centre position is defined as follows:

$$x_C(t) = \frac{\sum_{k=1}^N x_k(t)}{N} \quad (22)$$

$$y_C(t) = \frac{\sum_{k=1}^N y_k(t)}{N} \quad (23)$$

3.3.1. Initial conditions

The oil release can be instantaneous or continuous. When the leakage lasts several hours or even months, it can happen that the initial volumes spilled have been transported away from the release site when the last ones are released (Liu, et al., 2011). To model that,

MEDSLIK_II divides the total spill in sub-spills, consisting of a part of the oil released during an interval of time:

$$N_S = \frac{D_C}{T_C} \quad (24)$$

where D_C (s) is the release duration.

For instantaneous releases, the initial oil released is equal to the total oil released $V_S(x_C, t_0)$. However, for a continuous oil spill release, for each interval the volume released is

$$V_S(x_C, t_0) = R_C T_C \quad (25)$$

where R_C is the oil spill rate.

During an instantaneous release, N particles are released at the beginning, while in a continuous one, N_C particles are released every T_C :

$$N_C = \frac{N}{N_S} \quad (26)$$

The initial particle volume can be written as

$$\partial(n_k, t_0) = \frac{N_S V_S(x_C, t_0)}{N} \quad (27)$$

And also the evaporative and non-evaporative oil volume components:

$$\partial_E(n_k, t_0) = \left(1 - \frac{\partial_{NE}}{100}\right) \partial(n_k, t_0) \quad (28)$$

$$\partial_{NE}(n_k, t_0) = \frac{\partial_{NE}}{100} \partial(n_k, t_0) \quad (29)$$

Where ∂_{NE} is the percentage of the non-evaporative component of the oil that depends on the oil type.

The first thin and thick area values are taken from the initial surface amount of oil released using relative thicknesses and F , which is the area ratio. These three values are defined as input.

$$A^{TN}(t_0) = F A^{TK} \quad (30)$$

$$A^{TK}(t_0) = \frac{V_S(x_C, t_0)}{T^{TK}(x_C, t_0) + F T^{TN}(x_C, t_0)} \quad (31)$$

3.4. Time rate of change of slick state variables

Following Equation 11, the time rate of change of oil volume is written as

$$\frac{\partial V_S}{\partial t} = \frac{\partial V^{TK}}{\partial t} + \frac{\partial V^{TN}}{\partial t} \quad (32)$$

Figure 4 shows the three main processes that induce changes of the surface oil volume. They are known as weathering processes: evaporation, dispersion and spreading. The first one acting on the oil slick is evaporation, since initially the main volume is on the surface. In addition, for the first hours, the spill spreads mechanically due to gravitational forces.

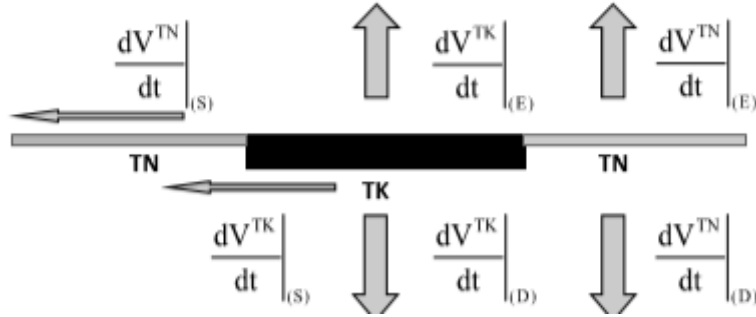


Figure 4: Weathering processes using Mackay's approach: evaporation (E), dispersion (D) and spreading (S) (De Dominicis, et al., 2013)

The three processes are considered separately for the thick and thin slick and only at the slick centre. Therefore, the forecast equations are

$$\frac{dV^{TK}}{dt} = \frac{dV^{TK}}{dt}_{(E)} + \frac{dV^{TK}}{dt}_{(D)} + \frac{dV^{TK}}{dt}_{(S)} \quad (33)$$

$$\frac{dV^{TN}}{dt} = \frac{dV^{TN}}{dt}_{(E)} + \frac{dV^{TN}}{dt}_{(D)} + \frac{dV^{TN}}{dt}_{(S)} \quad (34)$$

Each term of these equations is described in detail in Appendices B1, B2 and B4 in De Dominicis, et al (2013) paper, given in terms of modified Mackay fate algorithms for evaporation, dispersion and spreading.

Following Mackay's assumptions, T^{TN} does not change. Hence, A^{TN} is calculated as

$$\frac{dA^{TN}}{dt} = \frac{1}{T^{TN}} \frac{dV^{TN}}{dt} \quad (35)$$

Where

On the other hand, for the thick slick

$$\frac{dV^{TK}}{dt} = T^{TK} \frac{dA^{TK}}{dt} + A^{TK} \frac{dT^{TK}}{dt} \quad (36)$$

The area of the thick slick only changes due to spreading, so

$$\frac{dA^{TK}}{dt} = \frac{dA^{TK}}{dt}_{(S)} \quad (37)$$

V^{TK} is updated using Equation 34 and the thickness changes are calculated by

$$T^{TK} = \frac{V^{TK}}{A^{TK}} \quad (38)$$

3.5. Time rate of change of particle oil volume state variables

After the transformation processes have acted on the oil slick, the particle oil volumes are changed. For all particle status index, the evaporative oil particle volume changes following the empirical relationship

$$\partial_E(n_k, t) = \left[1 - \frac{\partial_{NE}}{100} - f^{(E)}(x_C, t) \right] \partial(n_k, t) \quad (39)$$

Where $f^{(E)}$ is the fraction of oil evaporated defined as:

$$f^{(E)}(x_C, t) = \frac{V^{TK}(x_C, t)_{(E)} + V^{TN}(x_C, t)_{(E)}}{V^{TK}(t_0) + V^{TN}(t_0)} \quad (40)$$

For both surface and dispersed particles, the non-evaporative oil component does not change, while a certain fraction of the non-evaporative oil component of a beached particle can be modified due to adsorption processes occurring on a particular coastal segment, seeping into the sand or forming a layer on rocky shore. For beached particles, the non-evaporative oil component is then

$$\partial_{NE}(n_k, t) = \partial_{NE}(n_k, t_0) 0.5^{\frac{t-t_0}{T_s(L_i)}} \sigma(n_k, t) = -i \quad (41)$$

where t_0 is the instant when the particle passes from surface to beached status and vice versa, $T_s(L_i)$ is a half-life for seepage or any other mode of permanent attachment to the coasts. It describes the “absorbency” of the shoreline by describing the rate of entrainment of the oil after it has landed at a given shoreline (Shen, et al., 1987). The half-life depends on the coastal type.

3.6. Time rate of change of particle positions

Immediately upon entering into a water body, the spilled oil spreads and forms a surface slick which covers a large area of the water surface and can be moved about by the action of winds, waves or currents (Shen, et al., 1987).

The evolution of the particle positions is given by n_k uncouple Langevin equations:

$$\frac{dx_k(t)}{dt} = A(x_k, t) + B(x_k, t) \partial \xi(t) \quad (42)$$

where the tensor A represents the deterministic part of the flow field and B the stochastic term together with ξ which is a random factor.

If we define the Wiener process

$$W(t) = \int_0^t \partial(\sigma) \delta \sigma \quad (43)$$

and apply the $It\bar{o}$ assumption (Tompson & Gelhar, 1990), Equation 42 becomes equivalent to the $It\bar{o}$ stochastic differential equation:

$$dx_k(t) = A(x_k, t)dt + B(x_k, t)dW(t) \quad (44)$$

where dW is a random increment.

The Wiener process describes the path of a particle due to Brownian motion modelled by independent random increments $d\mathbf{W}(t)$ sampled from a normal distribution with zero mean and second order moment dt . Hence, $d\mathbf{W}(t)$ in Equation 44 can be replaced by a vector \mathbf{Z} of independent random numbers, normally distributed, i.e. $\mathbf{Z} \sim N(0,1)$, and multiplied by \sqrt{dt} :

$$dx_k(t) = A(x_k, t)dt + B(x_k, t)\mathbf{Z}\sqrt{dt} \quad (45)$$

The unknown tensors $A(x_k, t)$ and $B(x_k, t)$ are written as (Risken, 1984):

$$dx_k(t) = \begin{bmatrix} U(x_k, t) \\ V(x_k, t) \\ W(x_k, t) \end{bmatrix} dt + \begin{bmatrix} \sqrt{2K_x} & 0 & 0 \\ 0 & \sqrt{2K_y} & 0 \\ 0 & 0 & \sqrt{2K_z} \end{bmatrix} \begin{bmatrix} Z_1 \\ Z_2 \\ Z_3 \end{bmatrix} \sqrt{dt} \quad (46)$$

where K are the turbulent diffusivity coefficients.

For particles at the surface and dispersed, Equation 46 takes the form

$$dx_k(t) = \begin{bmatrix} U(x_k, y_k, z_k, t) \\ V(x_k, y_k, z_k, t) \\ 0 \end{bmatrix} dt + \begin{bmatrix} dx'_k(t) \\ dy'_k(t) \\ dz'_k(t) \end{bmatrix} \quad (47)$$

The particle position does not change for particles at the surface. It can only change when the particle becomes dispersed and the horizontal velocity at the vertical position of the particle is used to displace the dispersed particles.

The Equation 47 can be expanded in different components according to the particle status index:

$$\begin{cases} \sigma = 0 & dx_k(t) = [U_C(x_k, y_k, 0, t) + U_W(x_k, y_k, 0, t) + U_S(x_k, y_k, 0, t)]dt + dx'_k \\ \sigma = 1 & dx_k(t) = U_C(x_k, y_k, 0, t)dt + dx'_k \end{cases} \quad (48)$$

where U_C is the Eulerian current velocity due to non-local wind, U_W is due to local wind and U_S is the velocity due to wave-induced currents or Stokes drift.

3.6.1. Current and local wind velocity terms

Ocean currents near the surface are generated by the atmospheric forcing. Although it can be subdivided into buoyancy fluxes and wind stresses, the last one is the most important in terms of kinetic energy of the induced motion (Wunsch, 1998). The wind-induced currents are attributable to non-local winds, and are dominated by geostrophic or quasi-geostrophic

dynamic balances (Pedlosky, 1986), where the pressure gradient force is balanced by the Coriolis effect and creates a flow parallel to the isobars. By definition, geostrophic and quasi-geostrophic motions have a timescale of several days and characterize oceanic mesoscale motion, a very important component of the large-scale flow field included in \mathbf{U} . These currents dominate below the mixed layer, which its dynamics are typically considered ageostrophic. The dominant time-dependent, wind-induced currents in the surface layer are the Ekman currents due to local winds (Price, et al., 1987). All these components have to be considered in the \mathbf{U}_C field in Equation 48.

Ekman transport is described in Figure 5; surface currents flow at a 45° angle to the wind due to a balance between the Coriolis force and the drags generated by the wind and the water (Mann, 2006). If the ocean is divided vertically into thin layers, the main value of the velocity decreases until it dissipated. The direction also shifts slightly across each subsequent layer (right in the northern hemisphere, left in the southern hemisphere). This is called Ekman spiral (Knauss, 1978). If all flow over the length of the spiral is integrated, the net transportation is at 90° to the right (left) of the surface wind in the northern (southern) hemisphere (Colling, 2001).

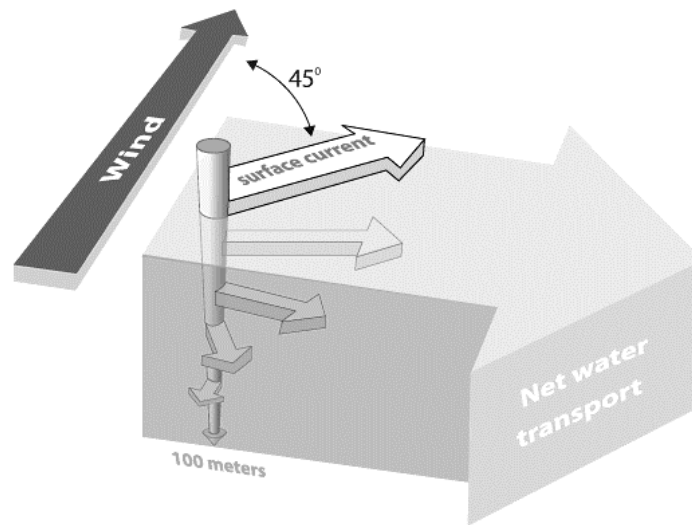


Figure 5: Ekman transport graphic

Therefore, Ekman currents at the surface can be parametrized as a function of wind intensity and angle between winds and currents, i.e.

$$U_W = \alpha [W_x \cos \beta + W_y \sin \beta] \quad (49)$$

$$V_W = \alpha [-W_x \sin \beta + W_y \cos \beta] \quad (50)$$

where W_x and W_y are the wind zonal and meridional components and α and β are two parameters referred as drift factor and drift angle.

Current velocity fields can be obtained from analyses and forecasts produced by high-resolution ocean general circulation models (OGCMs).

3.6.2. Wave current term

Waves push pollutants by wave-induced velocities that are known as Stokes drift velocity, U_S . It has to be added to the currents from OGCMs since most of the ocean models are not coupled with wave models (Röhrs, et al., 2012). Stokes drift is the net displacement of a particle in a fluid due to wave motion, resulting essentially from the fact that the particle moves faster forward when the particle is at the top of the wave circular orbit than it does backward when it is at the bottom of its orbit. Wave-driven transport is often ignored, although it may be the dominant mechanism transporting oil to adjacent beaches and coastal wetlands, whose environment has a big susceptibility to oil spills. It provides a natural mechanism for beaching of surface oil, one of the most damaging outcomes of a coastal oil spill (Sobey & Barker, 1997).

Considering the surface, the Stokes drift velocity intensity in the direction of the wave propagation is

$$D_S(z = 0) = 2 \int_0^\infty \partial K(\partial) S(\partial) d\partial \quad (51)$$

where w is angular frequency and $S(w)$ is wave spectrum.

To implement Equation 51, it is considered that the direction of the wave propagation is the same as the wind direction. Therefore,

$$U_S = D_S \cos \vartheta \quad (52)$$

$$V_S = D_S \sin \vartheta \quad (53)$$

Where ϑ is the wind direction.

3.6.3. Turbulent diffusivity terms

It is assumed that the particle moving through the fluid gets a random impulse at each time step, due to the action of incoherent turbulent motions and that it has no memory of its previous turbulent displacement:

$$dx'_k(t) = (2r - 1)\delta \quad (54)$$

Where d is the particle mean path and r is a random real number.

The mean square displacement of Equation 54 is

$$|dx'_k(t)|^2 = \int_0^1 [(2r - 1)\delta]^2 dr = \frac{1}{3} \delta^2 \quad (55)$$

while the mean square displacement of the turbulent terms in Equation 47 is $dx'_k(t)^2 = 2Kdt$. Equalizing both terms the following is obtained:

$$\delta^2 = 6K_x dt$$

$$\delta^2 = 6K_y dt$$

$$\delta^2 = 6K_z dt \quad (56)$$

Replacing these terms in Equation 54, it is possible to write the stochastic transport terms:

$$\begin{aligned} dx'_k(t) &= Z_1 \sqrt{2K_x dt} = (2r - 1) \sqrt{6K_h dt} \\ dy'_k(t) &= Z_2 \sqrt{2K_y dt} = (2r - 1) \sqrt{6K_h dt} \\ dz'_k(t) &= Z_3 \sqrt{2K_z dt} = (2r - 1) \sqrt{6K_v dt} \end{aligned} \quad (57)$$

where K_h and K_v are prescribed turbulent horizontal and vertical diffusivities.

3.7. Numerical considerations

In this section, the interpolation method between input fields and the oil tracer grid, to the numerical scheme used to solve Equations 33, 34 and 47, to the model time step and to the oil tracer grid selection is explained.

3.7.1. Interpolation method

The environmental variables which are used in this model (atmospheric wind, ocean currents and sea surface temperature) are normally supplied on a different numerical grid than the oil slick centre or particle locations. Therefore, to calculate the advection process, it is necessary to compute the currents and winds at the particle locations. However, for the transformation processes calculation, the sea surface temperature and winds are interpolated at the slick centre.

To show these interpolation processes, (x_E, y_E, z_E) is designed as the numerical grid on which the environmental variables are provided by the Eulerian models.

A pre-processing procedure is needed to reconstruct the currents in the area between the last water grid node of the oceanographic model and the real coastline. MEDSLIK_II extrapolates the currents in a way that gives a velocity field to the land points:

$$q_{x_E(i), y_E(i)} = \frac{q_{x_E(i+1), y_E(i)} + q_{x_E(i-1), y_E(i)} + q_{x_E(i), y_E(i-1)} + q_{x_E(i), y_E(i+1)}}{N_{\phi}} \quad (58)$$

Then, the winds and currents are computed at the particle position (x_k, y_k) for a fixed depth z_E with the following interpolation algorithm:

$$q1 = q_{x_E(i), y_E(i)} [x_E(i+1) - x_k]$$

$$q2 = q_{x_E(i+1), y_E(i)} [x_k - x_E(i)]$$

$$q3 = q_{x_E(i), y_E(i+1)} [x_E(i+1) - x_k]$$

$$q4 = q_{x_E(i+1),y_E(i+1)}[x_k - x_E(i)]$$

$$q_{x_k,y_k} = \frac{(q1+q2)[y_E(i+1)-y_k] + (q3+q4)[y_k-y_E(i)]}{\Delta x_E \Delta y_E} \quad (59)$$

where (x_k, y_k) is the particle position referenced to the oil tracer grid, $(x_E(i), y_E(i))$ and subsequent are the external four grid points.

The same algorithm is used to interpolate to the oil slick centre, $(x_c(t), y_c(t))$ the wind and sea surface temperature.

Besides, a vertical interpolation of the currents at the particle positions is also needed:

$$q_{x_k,y_k,z_k} = \frac{1}{z_E(i) - z_E(i+1)} \{q_{x_k,y_k,z_E(i+1)}[z_E(i) - z_k] + q_{x_k,y_k,z_E(i)}[z_k - z_E(i+1)]\} \quad (60)$$

3.7.2. Numerical time integration scheme

The Lagrangian horizontal particle motion, Equation 41, is solved using a Euler forward scheme as follows

$$x_k(t + \Delta t) = x_k(t) + U(x_k, t)\Delta t + \Delta x'_k(t) \quad (61)$$

where $x_k(t)$ represents the particle position at the current time step.

Equations 33 and 34 are also solved the same way as before but with a different time step, so-called weathering time step,

$$V^{TK}(t + \delta t) = V^{TK}(t) + \frac{dV^{TK}}{dt} \delta t \quad (62)$$

$$V^{TN}(t + \delta t) = V^{TN}(t) + \frac{dV^{TN}}{dt} \delta t \quad (63)$$

The two processes above described are not solved with the same speed: transformation processes are faster than advection-diffusion processes. Since transformation equations are stiff, to integrate them it is necessary that the time step is shorter, a fraction, of the Lagrangian time step (Butenschön, et al., 2012).

3.7.3. Particle status updates

After the particles have moved for a Lagrangian time step, their oil volume and status are updated. A particle becomes dispersed if the following probability function

$$P^{(D)}(t) = \frac{f^{(D)}(x_c, t) - f^{(D)}(x_c, t - \Delta t)}{(1 - f^{(D)}(x_c, t - \Delta t))} \quad (64)$$

Is greater than a random number defined between 0 and 1:

$$r < P^{(D)}(t) = \nabla \sigma(n_k, t) = 1 \quad (65)$$

The factor $f^{(D)}(x_C, t)$ is defined as

$$f^{(D)}(x_C, t) = \frac{V^{TK}(x_C, t)_{(D)} + V^{TN}(x_C, t)_{(D)}}{V^{TK}(x_C, t_0) + V^{TN}(x_C, t_0)} \quad (66)$$

To evaluate the particles that adhere to the coast, it is checked whether the particle crosses the coastline defined by the line segments L_i . If it does, the particle is moved to the intersecting position and changes its status from surface to beached. This situation may not last for ever and the particle may go back to the water (Shen, et al., 1987). The probability that runs that phenomenon is

$$P^{(C)}(L_i, t) = 1 - 0.5^{\frac{\Delta t}{T_w(L_i)}} \quad (67)$$

Therefore,

$$r < P^{(C)}(t) = \nabla \sigma(n_k, t) = 0 \quad (68)$$

The model does not follow oil fraction that is permanently deposited on the coast; the whole particles are not lost as permanently beached, but only a fraction of them. The actual number of particles remains constant

The model just loses particle only when they get to the bottom. There is not a good parameterization that calculates the particles that actually reach the bottom: those that are located less than 20 cm from the bottom are automatically considered not dispersed anymore but at the bottom:

$$H_B(x_k, y_k) - z_k < 20cm \sigma(n_k, t) = 2 \quad (69)$$

3.7.4. Oil tracer grid and number of particles

It is important to take into account some considerations regarding the size of the oil tracer grid and the number of particles in order to avoid problems during the whole calculation process. Also, to ensure the correct reproduction of oil distribution in space and time.

Analysing the Equation 44, two spatial limitations can be extracted:

$$L_A = U\Delta t \approx 180m \quad (70)$$

$$L_T = \sqrt{K\Delta t} \approx 60m \quad (71)$$

where L_A is the advective scale and L_T the diffusivity scale.

Therefore, the spatial resolution and the model time step have to be chosen so

$$L_T < \delta x_T < L_A \quad (72)$$

Besides, a method is needed to estimate the minimum and maximum number of particles. Equation 19 gives the concentration at the surface, which at the initial moment can be

written, in the limit of one particle in the tracer grid cell and assuming no evaporation and beaching, using Equation 27, as

$$C_S(x_T, y_T, t) = \frac{N_S V_S(x_C, t_0)}{N} \frac{\rho}{\delta x_T \delta y_T} \quad (73)$$

Equation 69 can be used to determine the maximum and minimum number of particles, deciding first the maximum and minimum concentrations (which change depending on the scenario) and for a given tracer grid size:

$$N^{max} = \frac{N_S V_S(x_C, t_0)}{C_S^{min} \delta x_T \delta y_T} \rho \quad (74)$$

$$N^{min} = \frac{N_S V_S(x_C, t_0)}{C_S^{max} \delta x_T \delta y_T} \rho \quad (75)$$

All these procedures and equations are included in MEDSLIK-II code, developed by De Dominicis, et al. (2013). Further and inside calculations can be seen in the whole article referenced by the end of this paper.

The following sections present the structure of the code, together with all the modifications added so it is upgraded to a next level so it can read an extended type of currents and temperature data: ROMS files.

4. MEDSLIK II. Code Architecture

This chapter describes the structure of the code behind MEDSLIK II, including the inputs needed (both files and variables). In the Appendix of this paper, a list of all the variables with their descriptions can be found. In this section, the main architecture is described.

Medslsik II system is composed of six main parts:

- 1) Source code
- 2) Meteo-oceanographic files
- 3) Input data files
- 4) Script files to execute the model in a Linux operative system
- 5) Visualization software
- 6) Out-put data files

Figure 6 shows MEDSLIK II reference code architecture where all the codes are listed.

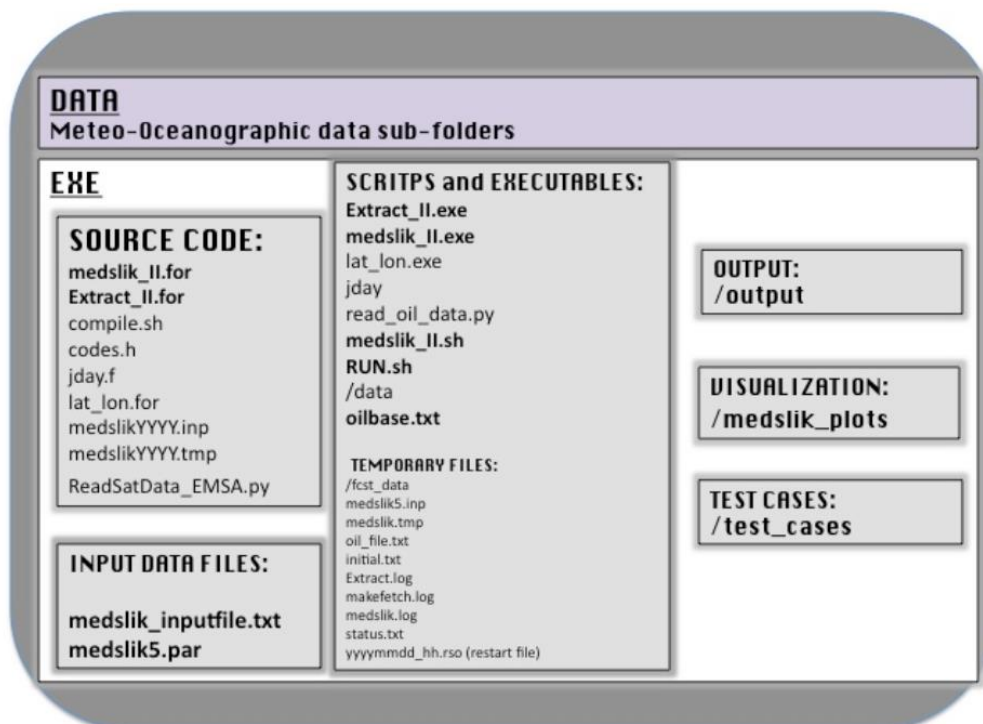


Figure 6: MEDSLIK-II Reference Code Architecture (De Dominicis, 2012)

4.1. Source Code

The folder source contains all the Fortran 77 based source codes. The main ones and, therefore, the ones that need most of the changes to upgrade the program, are:

- medslsik_II.for: simulates the oil spill.

- Extract_II.for: extracts and processes the required currents and temperature data from generic netCDF files.

4.2. Meteo-oceanographic files

MEDSLIK II has its own archive of bathymetry which is stored in EXE/data folder. New bathymetry files will need to be generated if one wants to run the program in specific areas not listed there.

Moreover, the program has a directory (DATA/fcst_data) where the user has to place the currents and wind files according, again, to the area where the simulation wants to be performed and also to the type of data (hourly or daily). In here it is necessary to create a new folder where to put the ROMS file. Table 2 shows a list of the initial meteo-oceanographic model outputs which can be used by MEDSLIK II.

MODEL OUTPUT	DIRECTORY	INPUT FILE STRING	FLAG USED IN THE CODES
Mediterranean Forecasting System (MFS) – hourly output	O1h	MFS	70
Adriatic Forecasting System (AFS) – hourly output	A1h	AFS	72
Mediterranean Forecasting System (MFS) – daily output	OPA	MFS24	10
Adriatic Forecasting System (AFS) – daily output	A24	AFS24	11
Sicily Channel Regional Model (SCRM) - hourly output	S1h	SCRM	71
Sicily Channel Regional Model (SCRM) - daily output	S24	SCRM24	12
Western Mediterranean Model (WME) - hourly output	WME	WME	75
Relocatable model	H3k		74
Tyrrhenian Forecasting System (TFS) - hourly output	T1h	TYRR	73
Tyrrhenian Forecasting System (TFS) - daily output	T24	TYRR24	13
ECMWF 0.5 ° winds	ECM	ECMWF025	25
ECMWF 0.25°	E25	ECMWF05	6

Table 2: Meteo-oceanographic model outputs initially run by MEDSLIK-II

4.3. Input Data files

Together with the currents and bathymetry, information regarding the spill needs to be introduced in the model. The different variables are manually inserted in two different files:

- medslk_inputfile.txt: contains spill data such as location, duration, type of oil and others. In the Appendix, a list and description of all variables can be found.

- medslk5.inp: inhere the user establishes the simulation parameters such as the drift angle or the diffusivity. Again, in the Appendix there is a complete list and description of every parameter.

4.4. Script files and executables

The script RUN.sh first launches the model run (medslk_II.sh) and afterwards the visualization execution (medslk_plots/medslk_plots.sh). The operations performed by the Linux shell script medslk_II.sh are listed below. The modification of the original program maintains this structure.

1. Read input data: medslk_inputfile.txt is processed.
2. Read the oil characteristics (using the routine read_oil_data.py) from the oil-type database (oilbases.txt and oil_list.txt).
3. Read slick contour. It can be read from satellite data file or from medslk_inputfile.txt (if the coordinates have been entered manually).
4. Save input data in the medslk5.inp file (which is read by medslk_II.exe)
5. Area selection: the routine lat_lon calculates the geographical limits of the area affected by the spill (assuming that the slick travels at less than 1.5 nauticalmiles/h from the spill site).
6. Check the currents and wind files needed for the simulation.
7. Extract currents, wind and SST data: this section calls the routine Extract_II.exe, one of the source codes that needs major changes due to the different input file (ROMS).
8. Run: medslk_II.exe is called so the simulation of the transport and weathering of the oil is performed.
9. Archive of the MEDSLIK_II output files, currents and winds used in the simulation in one unique folder (\$HOME/MEDSLIK_II_1.01/EXE/output).

4.5. Visualization software

The MEDSLIK_II visualization software reads the oil-on-surface output (.srf) and plots the oil-slick concentration in space and time, as well as the winds and currents. It generates maps for each time and stores them in the output directory.

The user can modify some parameters of the visualization such as the lat/lon limits or the time step between two images. The file medslk_plots.ncl contains all the modifiable parameters.

4.6. Output Data files

After each simulation the input files are saved in a subfolder inside the \$HOME/MEDSLI_II_1.01/EXE/output directory. It contains the following:

- The input files in text format (medslk_inputfile.txt, medslk5.inp and medslk.tmp).

- The satellite data file (if used).
- The parameter file in text format (medslik5.par).
- The medslik_plots.ncl visualization parameter file
- The medslik.fte file, which contains the trend over time of: the oil volume spilled, the percentage of oil evaporated, the percentage of oil on the surface, the percentage of oil dispersed, the percentage of oil on the coast and other parameters.
- outhhhh.srf files: contain the values of the oil concentration on the surface.
- outhhhh.dsp files: contain the values of the dispersed oil concentration.
- outhhhh.cst files: contain the values of the oil concentration on the coast.

In addition, the folder output contains one subfolder (plot) containing two subfolders where the data of the wind and currents in the area affected by the spill is stored.

5. MEDSLIK_II. Input files analysis

5.1. Introduction

All the information related to the currents, winds, temperature and bathymetry is stored in netCDF format files.

The Network Common Data Form (netCDF) software was developed by Unidata, a National Science Foundation-sponsored program empowering U.S. universities which has extended its influence around the world. It works as an I/O library, which can be called by C, FORTRAN, C++ and other languages. The library stores and retrieves data in self-describing, machine-independent datasets in the form of arrays. An array is an n-dimensional rectangular structure containing terms which all have the same data type. The type of data encompasses from single-point observations and time series to satellite or radar images. Array values are accessed directly, without knowing how data is stored. Extra information such as units is stored with the data (Rew, et al., 2016).

The netCDF libraries allow simultaneous access to multiple netCDF datasets which are identified by ID numbers in addition to ordinary file names.

Each dataset contains dimensions, variables and attributes. The dimensions have a name and a length, which is a positive integer. The variables have a name and an ID number. They represent an array of values of the same type. Each variable has a name, a data type, and associated attributes. It is important to identify these aspects so they can be properly called from the main program.

MEDSLIK II is prepared to work with netCDF files in a certain way. Here relays the aim of this dissertation, to upgrade MEDSLIK II so it can read an extensively used netCDF type of file: ROMS. The following section describe ROMS structure, although first, the original input files are reviewed so it is easier to identify conflict points.

5.2. MEDFF files

The Medff system provides with one file for each variable: temperature, u-currents and v-currents. One file contains hourly the information of one day. However, this system does not provide the data from 00:00 to 23:59; instead, it is given from 13:00 to 12:59 of the following day.

Each variable is calculated in the middle of the cell, so the string where they are stored has the same size: $imx \times jmx \times kmx \times ktmx$ (longitude length, latitude length, depth levels, measurement hours). Important is to notice that the depth levels are measured from the surface down, levels that are constant at any (lon, lat) position. There is a variable which stores the depth values in meters. Figure 7 shows a diagram of how the data is stored.

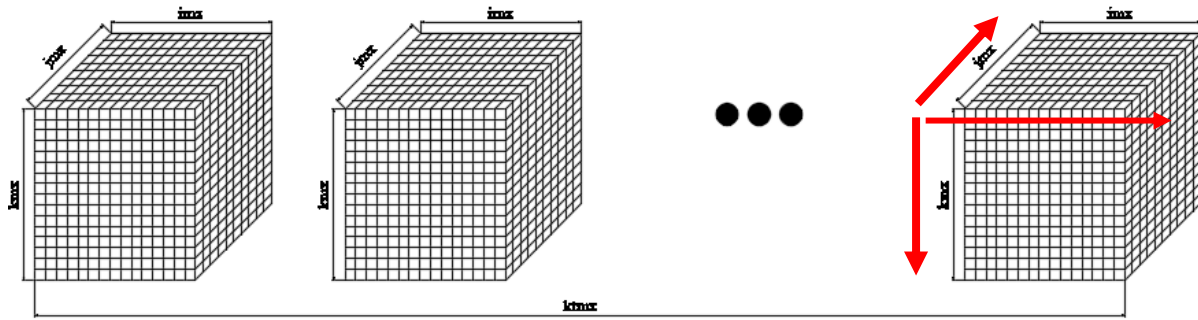


Figure 7: Data storage of Medff files and reading direction

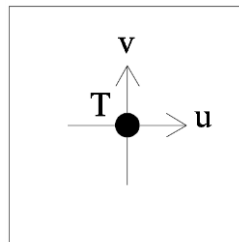


Figure 8: Point of measurement of each variable

The file also contains information relatively the longitude and the latitude of each cell centre, although the program does not use it because it works with already set up areas.

5.3. ROMS files

ROMS is a free-surface, terrain-following, primitive equations ocean model widely used by the scientific community for a diverse range of applications. The data resolution is quite convenient, since the user can adjust both vertical and horizontal resolution.

A unique ROMS file contains all three variables: temperature, u-currents and v-currents. Also, when extracting the file, the user can ask for the duration of the forecast. In other words, instead of having one file per day, there is only one file containing all the information. Since the user selects when downloading the data which period of time they want the information about, once they have the file, the only way of figuring out the date is throw an internal calculation based on the file's variable `scrum_time`. This variable refers to the time since initialization since 1st January at 00:00.

Special attention needs to be given to where ROMS calculates each variable. Scalar ones are at the cell's centre (temperature) while vector ones are calculated at the contour (u-currents and v-currents). Figure 9 shows the grid and the location of each variable.

Even though currents (both components) are defined in all the cells contour, when extracting data, one can usually just find the interior range of parameters, as it is shown in Figure 10. That results in not having any current data in the external contour. Furthermore, the dimensions of the three variables (temperature, u-currents and v-currents) are not the same, as it is shown in Table 3.

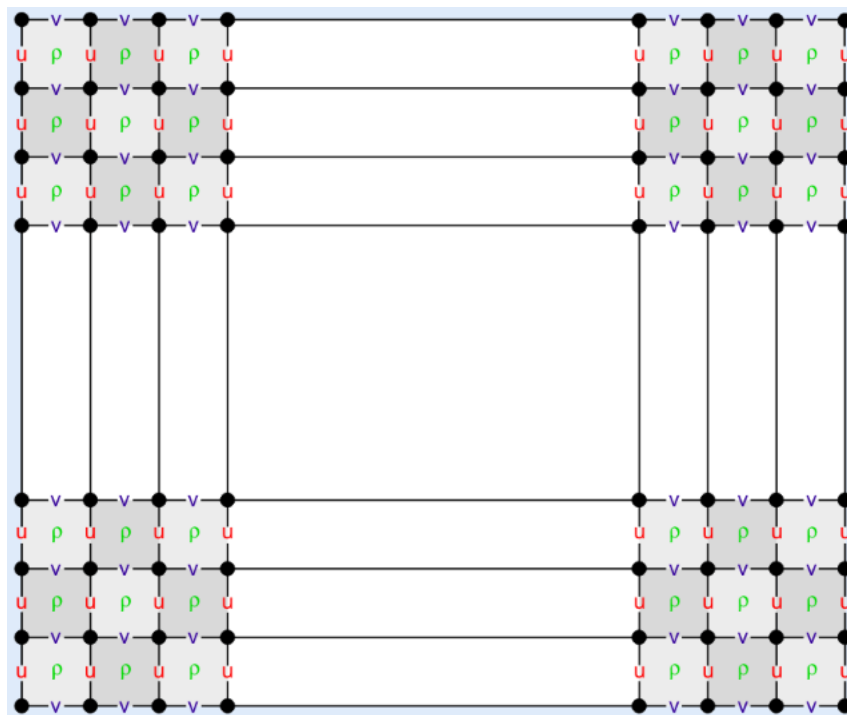


Figure 9: ROMS horizontal grid (Anon., 2016)

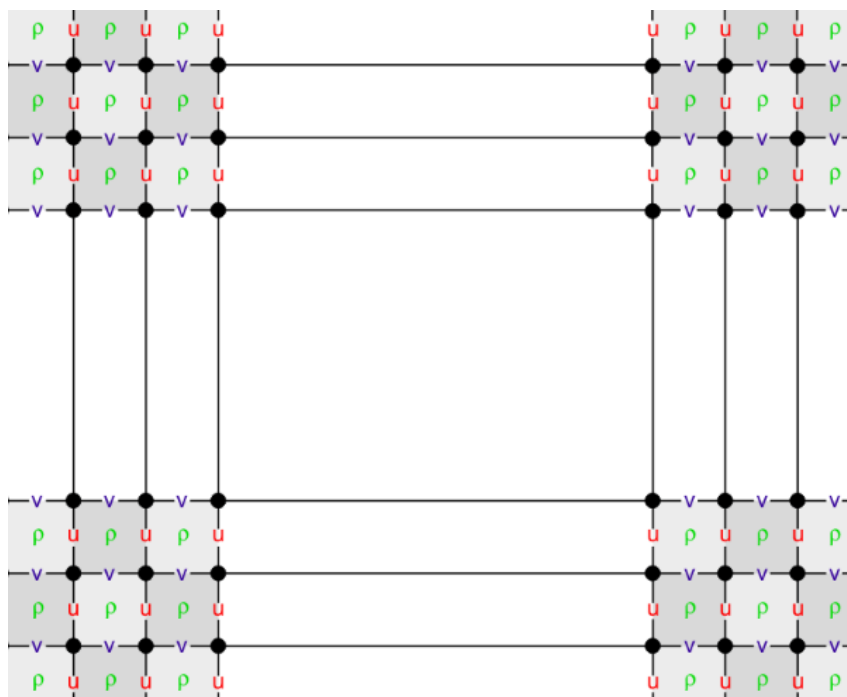


Figure 10: ROMS horizontal extracted grid (Anon., 2016)

Variable	Size
Temperature	imx x jmx x kmx x ktmx
u-currents	imx-1 x jmx x kmx x ktmx
v-currents	imx x jmx-1 x kmx x ktmx

Table 3: ROMS variables' size

Regarding depths, ROMS has its own reference system. It does not have, as Medff, horizontal levels at determined depths, which means that at shallow waters it stores null data at a certain point. Instead, it only takes into consideration the actual water levels by stretching curves over the ocean bottom. Figure 11 shows an example of these curves.

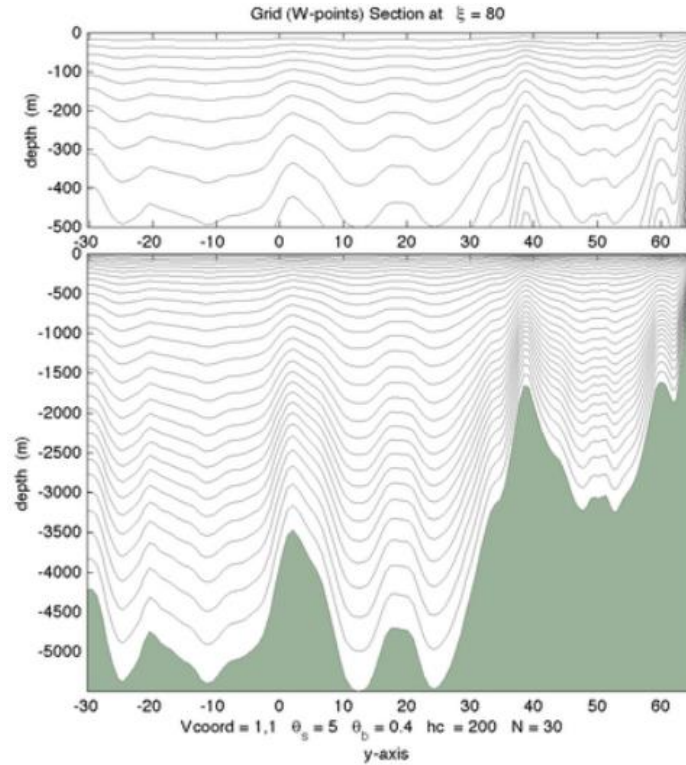


Figure 11: Example of ROMS vertical grid (Anon., 2015)

There is a simple equation which transforms from ROMS reference system to z-system in case it is needed to know to which z-depth a certain data belongs. In Section 6.2 this transformation is reviewed.

ROMS data starts at the bottom and goes up to the ocean surface. Figure 12 shows a diagram of how the data is stored (the same type of diagram as in Medff files has been used, although the depth levels do not correspond since they are not horizontal).

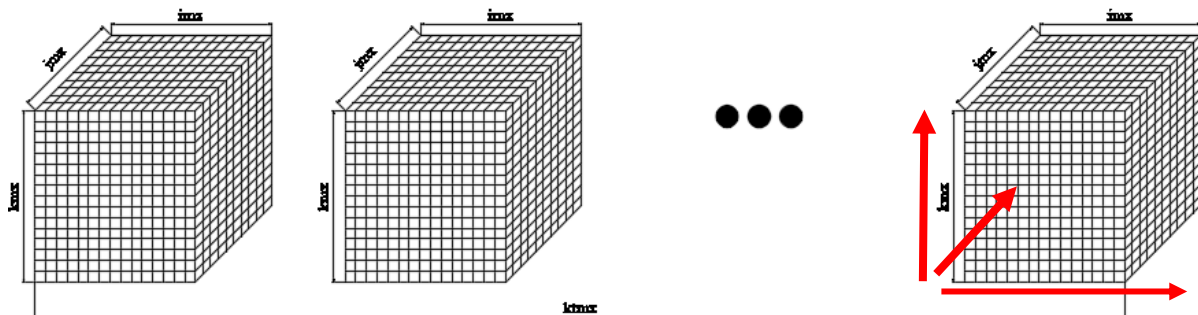


Figure 12: Data storage of ROMS files and reading direction

ROMS files contain many other variables regarding the currents and temperature. For this dissertation, special relevance is given to bathymetry at RHO-points variable and to the coefficients needed to transform S-coordinates to Z-coordinates.

5.4. Comparison between inputs

Once the structure of both input types is clear, the main differences are identified. The target is to create a subroutine that extracts the data from the ROMS file and transforms it so it is equal to the one MEDSLIK II is programmed to work with. Overall, the main differences are:

- Medff files store data of one day counting from 13:00 to 12:59 (including then data from two different calendar days). Therefore, there will be several files, one for each day. ROMS, however, contains all the information of every day in a unique file, starting at 00:00 to 23:59 of the last day of forecast.
- MEDSLIK_II identifies the files by its file name which has the following structure: YYMMDDHH. ROMS files have a standard name, "ocean_his". Therefore, when extracting the data, the files need to be renamed so medslk_II.for can read them.
- The original MEDSLIK_II is programmed in order to get information from three different files, one for each current component and one for the temperature. However, ROMS includes these three variables in a unique file.
- In the original program, one can find the bathymetry information already stored in a library in .bath files. However, the ROMS file includes the bathymetry of the area to model. Therefore, it is necessary to create the .bath file from the information in there. This will allow the user to perform the model in any area, not only in the ones predefined.
- The three variables of interest, both components of the currents and temperature, are taken from the centre of the grid cell. However, ROMS presents the currents on the border of the cell and the temperature in the centre (see Figure 10).

6. MEDSLIK_II. Modifications

6.1. Introduction

MEDSLIK_II was programmed to run at specific areas of the Mediterranean Sea. This dissertation brings a modification which makes MEDSLIK_II universal; it can be used anywhere if the user has the required input files.

In this section, the main additions and modifications to the code are listed and reviewed. One has to consider that minor changes are not mentioned, although in the appendix of this paper the entire code is attached with the modifications and additions marked.

Most of the changes affect the source code, specially Extract_II.for. This code processes the input files (in this case only one) based on the data of the spill and extracts the information needed for the simulation.

One of the targets of this dissertation is to create a clean and clear code so it can be read and modified easily by other users. Therefore, the new code follows the structure of the old one so it does not affect its harmony.

6.2. Extract_II.for

One of the ROMS highlights is its data resolution. Since the area covered by the data is rather small (compared with original MEDSLIK_II data, which covers the entire Mediterranean), it is also the area where MEDSLIK_II performs the modelling. Therefore, it is not necessary, as it is with the other type of files, to select a subarea from the original area. This results in having a much bigger grid (in terms of cells number), but with better resolution.

First step is to interpolate the u and v-currents strings so the values are located in the cells centre. Since only two values (from each border of the cell) are available, the interpolation is lineal

Since temperature values are already stored at the centre, after the interpolation is done, the three variables available to the next step, which is the vertical interpolation.

As it has been described before, ROMS data has a terrain-following vertical grid, so at shallow waters it does not store null numbers (as it would with a standard vertical grid). MEDSLIK_II works with the data at certain depths (10, 30 and 120 m) in all cells, so it is necessary to perform a transformation of the vertical grid to know the depth location of each cell:

$$z(x, y, \sigma, t) = \zeta(x, y, t) + [\zeta(x, y, t) + h(x, y)]S(x, y, \sigma) \quad (75)$$

$$S(x, y, \sigma) = \frac{h_c \sigma + h(x, y) C(\sigma)}{h_c + h(x, y)} \quad (76)$$

Where $S(x,y,\sigma)$ is a nonlinear vertical transformation functional, $\zeta(x,y,t)$ is the time-varying free-surface, $h(x,y)$ is the unperturbed water column thickness (a.k.a. bathymetry), σ is a fractional vertical stretching coordinate ranging from -1 to 0, $C(\sigma)$ is a nondimensional, monotonic, vertical stretching function ranging from -1 to 0 and h_c is a positive thickness controlling the stretching. It is important to notice that,

$$S(x,y,\sigma) = \begin{cases} 0 & \text{if } \sigma = 0, & C(\sigma) = 0 & \text{at free surface} \\ 1 & \text{if } \sigma = -1, & C(\sigma) = -1 & \text{at the ocean bottom} \end{cases} \quad [78]$$

As it is shown by the transformation above, ROMS files have a changing vertical grid throw time. This, again, gives even more precision to the modelling, since the data (u and v currents) is exactly measured at the exact depth.

Once the depth in meters string is available (z), several loops are performed to define the value of both u and v string that is located at the desired depth.

Finally, all the information which MEDSLIK_II requires to run is written in a file. The is a file for each time step.

ROMS forecast data for 23/09/15 05:00										
Subregion of the Mediterranean with limits:										
-8.91500 -8.60212 42.15000 42.35116 176 153 Geog. limits										
10805 0.0										
lat	lon	SST	u_srf	v_srf	u_10m	v_10m	u_30m	v_30m	u_120m	v_120m
42.1500	-8.9150	13.0000	0.0000	0.2037	0.1639	0.0257	0.0000	0.0594	0.0000	0.0000
42.1513	-8.9150	13.0000	0.0000	0.2223	0.1570	0.0376	0.0000	0.0769	0.0000	0.0000
42.1527	-8.9150	13.0000	0.0000	0.2591	0.1475	0.0639	0.0000	0.1142	0.0000	0.0000

Figure 13: Structure of a file extracted from the main ROMS file

6.3. Bathymetry and coast line data

A part from the u and v-currents and temperature, MEDSLIK_II also needs the bathymetry of the modelling area, its coast line and the type of coast for each coast line segment. MEDSLIK_II has a library where the user can find bathymetry, coast line and type of coast files for each area for which it was programmed to run for. Therefore, it is necessary that the user manually introduce these files for their case since ROMS files do not include this information (only the bathymetry which is extracted in Extract_II.for and stored in a file ready to be read by MEDSLIK_II).

These files need to have the following structure:

- Bathymetry (*.bath):
 - Heading
 - Min Longitude Max Longitude Min Latitude Max Latitude
 - No. 'x-cells' N° 'y-cells'
 - Cells bathymetry starting from the higher left one and moving to the left.
- Coast line (*.map)
 - Total no. of contours (coast lines)

-
- | | |
|--------------------------------|------------------------------|
| No of-points at the coast line | 0 (island) or 1 (open coast) |
| lon lat | |
| ... | |
- Type of coast (*.cst): For each coordinate of a coast point, the user must definí a type of coast according to this code:

1	sand beach
2	sand and gravel beach
3	cobble beach
4	rocky shore
5	seawall; concrete, wharf, etc
6	exposed headland
7	sheltered sand or gravel beach
8	sheltered rocky shore
9	sheltered marsh or mud flats

These three files have to be place at the MEDSLIK_II/EXE/data folder. For each simulation, these files need to be created accordingly.

6.4. medslk_II.for

medslk_II.for contains the simulation code based on the theory reviewed in section X. Minor modifications need to be applied since one of the improvement targets is to upgrade the code following its original structure: the ROMS file is processed so the information obtain has the same structure as the one medslk_II.for is programmed for.

7. MEDSLIK_II. Case study

To check the new code, a ROMS file containing data from Vigo has been used. The main effort has been generating through the routine `Extract_II` for forecast data files which the same structure are the previously admitted by the program. A test case of the original program (which modelled a region of Algeria) has also been used to compare different aspects.

In this case, the ROMS file contains information of a 176x153x10x169 grid. This means a 7-days forecast of the region showed in

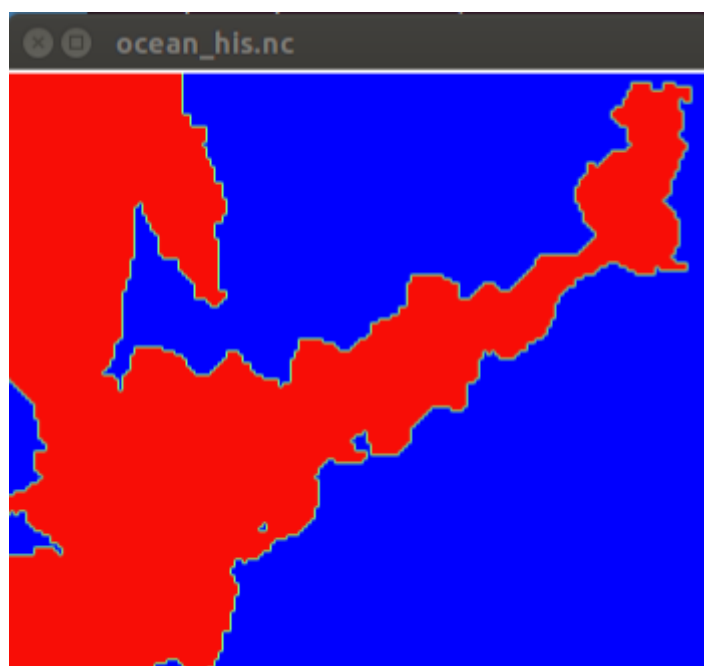


Figure 14: Region for the case study simulation

In this case, the grid will contain information regarding land areas. This increases unnecessarily the size of the files, resulting in a higher computational time if these points weren't considered. However, the geography and size of the area make impossible to reduce the grid because the leakage can disperse from its original point (e.g. Vigo's harbour located inside the ria) to any part of the current grid.

The files are correctly extracted and stored in the forecast folder for the subsequent simulation (a total of 192 files).

Nombre	Tamaño	Tipo	Modificado
roms15092200.opa	1,3 MB	Texto	17:47
roms15092201.opa	1,3 MB	Texto	17:48
roms15092202.opa	1,3 MB	Texto	17:48
roms15092203.opa	1,3 MB	Texto	17:48
roms15092204.opa	1,3 MB	Texto	17:49

Figure 15: Partial view of the files generated by `Extract_II` for

The bathymetry and coast line where already available. The coast line includes both Cíes islands although only part of them are considered in the simulation (see Figure 14).

Finally, medslk_II.for processes all input data so files containing oil concentration are created for each hour after the spill.

```

roms15092305.opa x  *out0004.dsp x
tons of dispersed oil
4      : Hours after start of spill
123.   : tons of oil released so far
42.240 -8.981 : Lat & Long of spill location
150.0  : Pixel size (m) for spill plotting
%evap  %srf  %disp  %cst  srf vol  Tot srf vol
30.4800 69.4289 0.0911 0.0000 0.89258E+03 0.89258E+03
116     : Number of data points
Lat     Lon     tons/km2
42.2603 -8.913  0.23345E+00
42.2671 -8.905  0.23345E+00

```

Figure 16: Structure of the hourly output file

In this case, the graphic output is not valid due to the resolution. Further modifications need to be added to adapt ROMS resolution to the plot's. However, in Figure 17 one of the plots obtained in the case study is shown. This plot is useful to know the direction of the spill's movement. However, it is not really useful regarding numerical data.

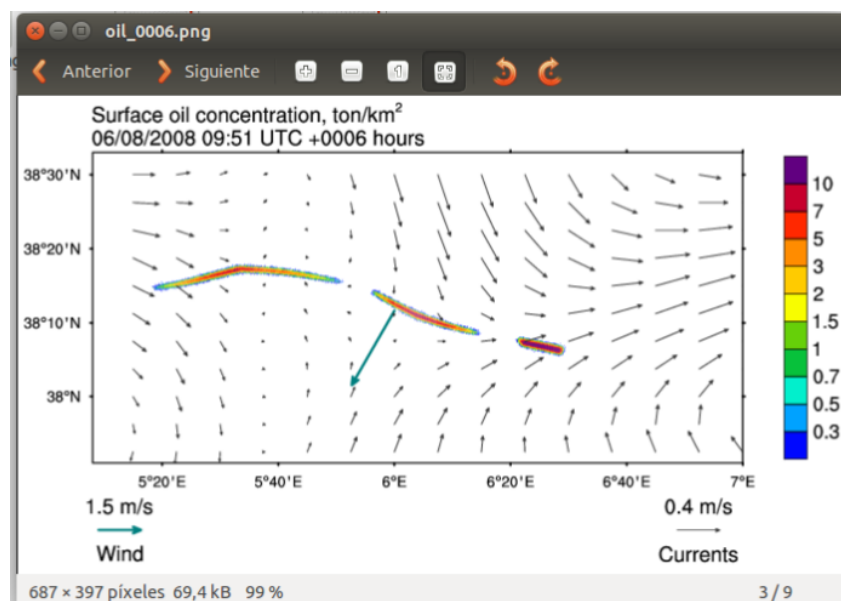


Figure 17: Plot of Algeria test

Overall, except the plot section, the model is considered as validated.

8. Conclusions and future modifications

The original MEDSLIK_II brings to the hydrocarbons modelling field a new system of both Lagrange and Stoke particle movement. This innovation needs to be universal, therefore, the software has to be able to process as many types of data as possible. This dissertation brings a modification of the original code so it is now able to process ROMS data, a widely used forecast system.

Further work needs to also be done to the plot routine. It is currently programmed for big areas' resolution so when simulating much smaller areas (as Vigo), its output results useless. It would be interesting to relate this function to the extract one so, the ROMS grid size is correlated to the plot resolution.

The grid which MEDSLIK_II uses is quadratic, which means that, sometimes, land data is considered, increasing the simulation time. Further modifications should allow to relocate the original grid so it is parallel to the coast (e.g.: when modelling Barcelona's harbour, which has an approximately 45° inclination, being able to locate the grid parallel to it). This would include interpolating again ROMS data, so it has to be carefully studied.

Understanding the original code has been one of the most complicated parts: as a free software, MEDSLIK_II should be readable and understandable and it is currently not the case. Therefore, one of the future added improvements should be the revision of the entire code so it is more universal. The subroutine added to Extract_II.for has followed this vision and every modification of any part of the generic code has been precisely specified.

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Input parameters in medslk_inputfile.txt

The following are the input data entered manually.

Simulation name (SIM_NAME). Name of the simulation (any name without blank spaces and symbols), e.g. *SIM_NAME=TEST*

Model data (MODEL). A string representing each of the different current model outputs for which MEDSLIK-II can read the data. For example, *MFS* represents the MFS hourly output, *MFS24* the MFS daily output, *AFS* the AFS hourly output and so on (for the complete list see Table 1), e.g. *MODEL=MFS*.

Wind data (WIND). A string representing each of the different wind fields for which MEDSLIK-II can read the data. *ECMF025* represents ECMWF data with a resolution of 0.25, while *ECMF05* represents ECMWF data with a resolution of 0.5 (for the complete list see Table 1), e.g. *WIND=ECMF025*.

Length of the Simulation (sim_length). The number of hours from the start of the spill or trajectory for which the prediction of position and state of the oil are required. This written using 4 characters, e.g. *sim_length=0072*.

Day of Spill/Start (day). The day on which the spill or the trajectory starts. This item must be written using 2 characters, e.g. *day=03*.

Month of Spill/Start (month). The month on which the spill or the trajectory starts. This item must be written using 2 characters, e.g. *month=02*.

Year of Spill/Start (year). The year on which the spill or the trajectory starts. This item must be written using 2 characters, e.g. *year=09*.

Hour of Spill/Start (hour). The hour of day between 0 and 23. This item must be written using 2 characters, e.g. *hour=08*.

Minutes of Spill/Start (minutes). The minutes after the hour of start, between 0 and 59, at which the spill or trajectory is started. This item must be written using 2 characters, e.g. *minutes=05*.

Location of the Spill/Start (lat_degree). The latitude at which the spill occurred is entered in degrees and decimal minutes. This item has 2 characters, e.g. *lat_degree=42*.

Location of the Spill/Start (lat_minutes). The latitude at which the spill occurred or the trajectory started is entered in degrees and decimal minutes. This item has 4 characters, e.g. *lat_minutes=22.20*.

Location of the Spill/Start (lon_degree). The longitude at which the spill occurred or the trajectory started is entered in degrees and decimal minutes. This item has 2 characters, e.g. *lon_degree=10*.

Location of the Spill/Start (lon_minutes). The longitude at which the spill occurred or the trajectory started is entered in degrees and decimal minutes. This item has 4 characters, e.g. *lon_minutes=55.50*.

Duration of the Spill/Releases (duration). The number of hours during which oil or pollutant was spilling. For an instantaneous spill enter 0. It is written using 4 characters, e.g. *duration=0072* or *duration=0000*.

Rate of Spillage (spillrate). The rate (in tons per hour) at which oil was spilt. For an instantaneous spill, the total volume has to be written, e.g. *spillrate=10.50*.

Slick age (age). The slick age, which can be 0, 24 or 48 hrs, e.g. *age=0*.

Oil tracer grid size (grid_size): Each time the results are printed in one of the output files, the particles are aggregated inside 'pixels', the size of which is specified by the *grid_size* parameter, e.g. *grid_size=150*.

Oil (OIL). If the precise name of the oil is known, write *OIL=NAME*, if it is unknown write *OIL=API*.

Type of Oil. The name of the oil type that has been spilt can be chosen from a list of over 200 oils (*oil_list.txt*) e.g. *OIL_TYPE=Arabian Heavy*. If the precise name of the oil is unknown, you must enter the API number of the oil, e.g. *OIL_TYPE=17*.

Point or areal source of spill (ContourSlick and SAT_DATA): MEDSLIK-II allows the simulation of (1) a point source of spill or (2) an areal source of spill with manual insertion of contour coordinates or (3) an areal source of spill using satellite data.

- 1) Use *SAT_DATA=NO* and *ContourSlick=NO* to perform a simulation of a point source of spill (no need to fill the Number of Slicks -- *Nslick* and list of latitude and longitude of slick points contour -- *S1lon[1], S1lat[1], S1lon[2], S1lat[2]...*)
- 2) Use *SAT_DATA=NO* and *ContourSlick=YES* to perform a simulation of an areal source of spill. If *ContourSlick=YES* is chosen, then the following parameters have to be specified (otherwise leave them blank):

Number of Slicks (Nslick): number of oil slick to be simulated, written using 1 character, e.g. *NSlick=2*.

List of latitude and longitude of slick points contour (S1lon[1], S1lat[1], S1lon[2], S1lat[2]...): latitude and longitude (in decimal degrees) of the oil slick polygon vertices.

- 3) Use *SAT_DATA=YES* and *ContourSlick=NO* to perform a simulation of an areal source of spill using satellite data (no need to fill the Number of Slicks -- *Nslick* and list of latitude and longitude of slick points contour -- *S1lon[1], S1lat[1], S1lon[2], S1lat[2]...*). When MEDSLIK-II is used for forecast of a slick observed by satellite or by other means, the data

for the observation is read from a file named `initial.txt` in the main model directory (`$HOME/MEDSLIK_II_1.01/EXE`). This file has been converted by the `ReadSatData.py` from a `.gml` or `.xml` file derived from the satellite image.

Satellite data is received from EMSA in a file of type `*.gml` which can be visualized on Google Earth. Such files may contain data for several oil slicks, with the boundary of each digitized to a fine resolution, especially in the case of a *gml* file.

If `SAT_DATA=YES` is chosen, the following parameters have to be filled (otherwise leave them blank):

namefileGML has to be filled with the name of the GML file (e.g. *namefileGML=ASA_WSM_1PNACS20080806_095116_000000612071_00022_33643_0001.N1.00000_Oil.gml*). The file has to be saved in the directory `$HOME/MEDSLIK_1.01/EXE`.

N_OS has to be filled with the number of the oil slick in the file to be simulated (e.g. *N_OS=1*)

Input parameters in medslk5.par

The following will provide a brief description of the significance of the parameters in the medslk5.par. These are the parameters that a user is most likely to want to change from their default values.

Stokes drift correction. Choosing 01 allows the model to use the wave-induced velocity (Stokes drift) calculated using an empirical formulation. Choosing 00 Stokes drift velocity will not be applied. The default value is 01.

Wind correction (Drift Factor). The drift speed of the slick is equal to this factor multiplied by the wind speed. The default value is 0.

Wind correction (Drift Angle). The wind-driven drift of the slick occurs at this angle to the right of the wind direction. The default value is 0.0 degrees, which causes the slick to move directly downwind.

Variable Drift Angle. Choosing 01 allows the model to use a drift angle that decreases as the wind speed increases; a wind speed at which the drift angle is reduced by 50% must then be entered in the line below. The default is that such a reduction is not made.

Reduction of Forecast Wind Speed. When using forecast water circulation in a simulation, the forecast water velocities already include the effect of the wind forces on the water surface. It may thus be considered appropriate in some cases to reduce the wind speed used in the drift formula by a fraction of the winds used in the forecast. This can be done writing 01 in effective wind speed and entering in the line below the reduction fraction (between 0 and 1). The default is that such a reduction is not made.

Smagorinsky Scheme. Choosing 01 allows the horizontal diffusivity to be computed from the water currents using the Smagorinsky scheme. The default value is 0.

Horizontal Diffusivity. Enter the diffusivity that determines the horizontal diffusive spreading of the slick. The default value is 2.0 m²/s. A larger value will cause the slick to spread faster.

Vertical Diffusivities. The model allows the use of two values of vertical diffusivity: a larger value in the top well-mixed layer and a smaller value below the mixed layer. The defaults are 0.01 and 0.0001 m²/s respectively.

Depth of Mixed Layer. The default for this depth is 30 m.

Number of parcels. Diffusion and dispersion are modelled using a Monte Carlo algorithm, representing the oil by a large number of particles which are then given appropriate random displacements, and the resulting cloud of parcels used to estimate the concentration of the oil in the slick. MEDSLIK-II uses 10,000 parcels as the default, but the user can increase this up to 300,000.

Depths of Forecast Currents. The current fields are extracted from the Nectdf and are given in the text files in *\$HOME/MEDSLIK-II_1.01/EXE/fcst_data* at fixed depths. Whatever depths are used in the text files (they can only be changed by modifying the Extract_II.for code), the same depths must be entered in the parameters form. In the MEDSLIK-II_1.01 version the current fields are given at 3 depths (10 m, 30 m and 120 m) plus the surface.

Selection of currents for convection of slick. In the MEDSLIK-II_1.01 version it is possible to choose between 4 options: 00 for surface currents, 01 for 10 m deep currents, 02 for 30 m deep currents and 03 for 120 m deep currents. The default strategy is to use the surface velocities for advection of the slick and to ignore the wind drift altogether (by setting the drift factor equal to zero).

Number of Time Steps per Hour. The default value is 2. The default time step for computation of the convection and diffusion is 30 minutes. (A shorter step is used for the fate processes.) In general, this is adequate, but for a continuous spill with strong winds and/or currents, the 30-minute step may cause the computed slick to appear as a number of discrete slicks that do not merge for several hours. This lack of reality can be reduced by using a shorter time step.

Dimension of the Array used for representing the slick. Each time the results are printed in one of the output files, the particles are aggregated inside 'pixels', the size of which was entered in the **medslik_inputfile.txt** (**grid_size**). These pixels form an array the dimension of which is set by this parameter. The default array dimension is 2000×2000 and the maximum is 4000×4000. Choosing this maximum causes the run program to slow very significantly. On the other hand, too small a dimension causes the displayed slick to have straight, barrier-like, edges. If this occurs, you must either choose a larger array dimension or a larger pixel size.

Subroutine added to Extract_II.for

```

1  c-----
2  c MEDSLIK-II_1.01
3  c oil spill fate and transport model
4  c-----
5  c Extract_II.for
6  c This routine reads winds and currents from
7  c meteo-oceanographic model output (NetCDF files)
8  c-----
9  c Copyright (C) <2012>
10 c This program was originally written
11 c by Robin Lardner and George Zodiatis.
12 c Subsequent additions and modifications
13 c have been made by Michela De Dominicis.
14 c This version contains additions and modifications
15 c by Paula Martín Laguna so the program is able to process
16 c as inputs ROMS files.
17 c-----
18 c The development of the MEDSLIK-II model is supported by a formal agreement
19 c Memorandum of Agreement for the Operation and Continued Development of MEDSLIK-II
20 c signed by the following institutions:
21 c INGV - Istituto Nazionale di Geofisica e Vulcanologia
22 c OC-UCY - Oceanography Center at the University of Cyprus
23 c CNR-IAMC - Consiglio Nazionale delle Ricerche - Istituto per
24 c lo Studio dell'Ambiente Marino Costiero
25 c CMCC - Centro Euro-Mediterraneo sui Cambiamenti Climatici
26 c
27 c This program is free software: you can redistribute it and/or modify
28 c it under the terms of the GNU General Public License as published by
29 c the Free Software Foundation, either version 3 of the License, or
30 c any later version.
31 c
32 c This program is distributed in the hope that it will be useful,
33 c but WITHOUT ANY WARRANTY; without even the implied warranty of
34 c MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE. See the
35 c GNU General Public License for more details.
36 c You should have received a copy of the GNU General Public License
37 c along with this program. If not, see <http://www.gnu.org/licenses/>.
38 c-----
39
40     character regn*4, indate(30)*8, indate_wind(30)*8, fc_dir*120,
41     &          filename*9
42     common regn, alon1, alon2, alat1, alat2, numfiles, indate,
43     &          numfiles_wind, indate_wind, iviod, icurrents, fc_dir,
44     &          filename
45     integer len_dir
46 c-----
47 c read subregion limits & file dates. Adjust limits to lie on OPA grid
48 c-----
49     call getarg(1,fc_dir)
50     len_dir=120
51     do while(fc_dir(len_dir:len_dir).eq.' ')
52     len_dir=len_dir-1
53     enddo
54
55
56     open(1,file='medslik.tmp')
57     read(1,*) regn, icurrents, iwind
58     print*, icurrents
59     read(1,*) alon1,alon2
60     read(1,*) alat1,alat2
61     read(1,*) numfiles
62     if(icurrents.ne.100) then
63     do n=1,numfiles+1
64         read(1,'(a8)') indate(n)
65     enddo
66     read(1,*) numfiles_wind
67     do n=1,numfiles_wind
68         read(1,'(a8)') indate_wind(n)
69     enddo
70     else
71     read(1,'(a9)') filename
72     print*, filename

```

```

73      endif
74      read(1,*) iviod
75      close(1)
76
77      open(99,file='Extract.log')
78      if(icurrents.eq.10) call ExtractOPA(fc_dir,len_dir)
79      if(icurrents.eq.11) call ExtractADRI24(fc_dir,len_dir)
80      if(icurrents.eq.12) call ExtractSICI24(fc_dir,len_dir)
81      if(icurrents.eq.13) call ExtractTYRR24(fc_dir,len_dir)
82
83      if(icurrents.eq.70) call ExtractOPA_1hr(fc_dir,len_dir)
84      if(icurrents.eq.71) call ExtractSICI(fc_dir,len_dir)
85      if(icurrents.eq.72) call ExtractADRI(fc_dir,len_dir)
86      if(icurrents.eq.73) call ExtractTYRR(fc_dir,len_dir)
87      if(icurrents.eq.74) call ExtractRELO(fc_dir,len_dir)
88      if(icurrents.eq.75) call ExtractWESTMED(fc_dir,len_dir)
89
90      if(icurrents.eq.100) call ExtractROMS_1hr(fc_dir,len_dir,
91 & filename)
92
93      if(iwind.eq.6)      call ExtractECMWF(fc_dir,len_dir)
94      if(iwind.eq.25)     call ExtractECMWF25(fc_dir,len_dir)
95      stop
96      end
97
98      c*****
99      c      Extract medslk files from ROMS data 1hr
100     c*****
101     subroutine ExtractROMS_1hr(fc_dir,len_dir,filename)
102
103     parameter(ktmx=169, imx=176, jmx=153, kmx=10, imx_U=175,
104 & jmx_V= 152, theta_s=6, theta_b=0.9, hc=1)
105
106     real sc_r(10), cs_r(10)
107     real fmis !netcdf
108     parameter(fmis=0.) !netcdf
109     integer start(4), start_lonlat (2), start_mask(2), start_h(2),
110 & start_st(2), count(4), count_lonlat(2), count_mask(2),
111 & count_h(2), count_st(2) !netcdf
112     integer id, idlon, idlat, idU, idV, idT, idmask_rho, idh, idst !netcdf
113     integer Status !netcdf
114     integer msk(imx,jmx), mask(imx,jmx), st(ktmx,1)
115     real oplon(imx), oplat(jmx),
116 & ts(imx,jmx,kmx), u(imx,jmx,kmx), v(imx,jmx,kmx),
117 & ts_tmp(imx,jmx,kmx), u_tmp(imx,jmx,kmx),
118 & v_tmp(imx,jmx,kmx), lon_tmp(imx), lat_tmp(jmx),
119 & ts_169(imx,jmx,kmx,ktmx), u_169(imx,jmx,kmx,ktmx),
120 & v_169(imx,jmx,kmx,ktmx), lon(imx,jmx), lat(imx,jmx),
121 & u_in(imx_U,jmx,kmx,ktmx), v_in(imx,jmx_V,kmx,ktmx),
122 & z(imx,jmx,kmx), h(imx,jmx)
123     character Startd*6, filename*9, prdate*16, outfile*40,infile*120,
124 & heads*150, empty*80, regn*4, ora*2, ore*2, fc_dir*120,
125 & dia*2, hour*2, dayc*2, monthc*2
126     logical ex
127     integer t, o, kount, nore, len_dir, Startdi, Startdd, d, s, dur,
128 & month, day, dayS
129     common regn, alon1, alon2, alat1, alat2, numfiles, indate,
130 & iviod, icurrents
131     data udef /9999./, rhoa /1.19/
132
133     c-----
134     c      Read ROMS file
135     c-----
136     c Get to the directory
137
138     Status = 0
139     infile=fc_dir(1:len_dir)//'/fcst_data/ROMS/'
140 & //filename(1:9)//'.nc'
141
142     len_file=120
143     do while(infile(len_file:len_file).eq.' ')
144     len_file=len_file-1

```

```

145         enddo
146
147     c Open netCDF file
148
149         Status = nf_open(infile(1:len_file),nf_nowrite,id)
150         print *,id
151         call handle_err(Status)
152
153     c-----
154     c     ROMS horizontal grid
155     c-----
156     c Check of the variables from ROMS file
157
158         Status = nf_inq_varid (id, 'lon_rho', idlon)
159         call handle_err(Status)
160         Status = nf_inq_varid (id, 'lat_rho', idlat)
161         call handle_err(Status)
162         Status = nf_inq_varid (id, 'u', idU)
163         call handle_err(Status)
164         Status = nf_inq_varid (id, 'v', idV)
165         call handle_err(Status)
166         Status = nf_inq_varid (id, 'temp', idT)
167         call handle_err(Status)
168         Status = nf_inq_varid (id, 'scrum_time', idst)
169         call handle_err(Status)
170         Status = nf_inq_varid (id, 'mask_rho', idmask_rho)
171         call handle_err(Status)
172         Status = nf_inq_varid (id, 'h', idh)
173         call handle_err(Status)
174
175         print*,idh
176     c Since longitudes and latitudes at RHO points are available, the grid
177     c is already built. It's just necessary to extract the strings holding
178     c the data.
179
180     c Longitudes string (at RHO points)
181
182         start_lonlat(1) = 1
183         start_lonlat(2) = 1
184
185         count_lonlat(1) = imx
186         count_lonlat(2) = 1
187
188         Status = nf_get_vara_real (id, idlon, start_lonlat, count_lonlat,
189 &                                lon_tmp)
190         call handle_err(Status)
191         oplon=lon_tmp
192     c Latitudes string (at RHO points)
193
194         start_lonlat(1) = 1
195         start_lonlat(2) = 1
196
197         count_lonlat(1) = 1
198         count_lonlat(2) = jmx
199
200         Status = nf_get_vara_real (id, idlat, start_lonlat, count_lonlat,
201 &                                lat_tmp)
202         call handle_err(Status)
203         oplat=lat_tmp
204
205     c The spill will affect the entire grid due to the size of the area.
206     c Therefore, it is easy to update the coordinates of the RHO points
207     c and number of total cells affected by the spill.
208
209         alon1=oplon(1)
210         alon2=oplon(imx)
211         alat1=oplat(1)
212         alat2=oplat(jmx)
213
214         i_first = 1
215         i_last  = imx
216         j_first = 1

```

```

217         j_last = jmx
218
219         imax = imx
220         jmax = jmx
221
222     c Write information in the file Extract.log
223
224         write(99,*) 'i-limits   = ',i_first,i_last,imax
225         write(99,*) 'j-limits   = ',j_first,j_last,jmax
226         write(99,*) 'lon-limits = ',alon1,alon2,imx
227         write(99,*) 'lat-limits = ',alat1,alat2,jmx
228
229     c-----
230     c   read ROMS data file
231     c-----
232     c All the information regarding currents and temperature is stored in
233     c the same netcdf file, which has been already open to extract the
234     c longitudes and latitudes. In this section, a part from extracting
235     c the relevant strings, a interpolation is performed, since the data
236     c corresponding to the currents has been measured at the borders of the
237     c grid and MEDSLIK_II works with all the data at the centre of it.
238     c A linear interpolation is performed, taking into account that the
239     c borders of the grid do not have information, therefore no
240     c interpolation is possible there. More details can be found at the
241     c report.
242     c-----
243     c Extract U
244
245         start(1) = 1
246         start(2) = 1
247         start(3) = 1
248         start(4) = 1
249
250         count(1) = imx-1
251         count(2) = jmx
252         count(3) = kmx
253         count(4) = 1
254
255         do t = 1,ktmx
256             start(4)=t
257             Status = nf_get_vara_real (id, idU, start, count, u_tmp)
258             call handle_err(Status)
259             u_in(1:imx_U,1:jmx,1:kmx,t) = u_tmp(1:imx_U,1:jmx,1:kmx)
260         enddo
261
262     c Linear interpolation. Because of the data available,
263     c first and last columns can't be interpolated
264
265         u_169(1,1:jmx,1:kmx,1:ktmx)=u_in(1,1:jmx,1:kmx,1:ktmx)
266         u_169(imx,1:jmx,1:kmx,1:ktmx)=u_in(imx_U,1:jmx,1:kmx,1:ktmx)
267
268     c Interpolation for the rest
269
270         do l=2,imx_U
271             do m=1,jmx
272                 do n=1,kmx
273                     do o=1,ktmx
274                         u_169(l,m,n,o)=u_in(l-1,m,n,o)+
275                         & (u_in(l,m,n,o)-u_in(l-1,m,n,o))/2
276                     enddo
277                 enddo
278             enddo
279         enddo
280
281     c Extract V
282
283         start(1) = 1
284         start(2) = 1
285         start(3) = 1
286         start(4) = 1
287
288         count(1) = imx

```

```

289      count(2) = jmx-1
290      count(3) = kmx
291      count(4) = 1
292
293      do t = 1,ktmx
294      start(4)=t
295      Status = nf_get_vara_real (id, idV, start, count, v_tmp)
296      call handle_err(Status)
297      v_in(1:imx,1:jmx_V,1:kmx,t) = v_tmp(1:imx,1:jmx_V,1:kmx)
298      enddo
299
300      c Linear interpolation. Because of the data available,
301      c first and last rows can't be interpolated
302
303      v_169(1:imx,1,1:kmx,1:ktmx)=v_in(1:imx,1,1:kmx,1:ktmx)
304      v_169(1:imx,jmx,1:kmx,1:ktmx)=v_in(1:imx,jmx_V,1:kmx,1:ktmx)
305
306      c Interpolation for the rest
307
308      do l=1,imx
309      do m=2,jmx-1
310      do n=1,kmx
311      do o=1,ktmx
312      v_169(l,m,n,o)=v_in(l,m-1,n,o)+
313      & (v_in(l,m,n,o)-v_in(l,m-1,n,o))/2
314      enddo
315      enddo
316      enddo
317      enddo
318
319      c Extract T
320
321      start(1) = 1
322      start(2) = 1
323      start(3) = 1
324      start(4) = 1
325
326      count(1) = imx
327      count(2) = jmx
328      count(3) = kmx
329      count(4) = 1
330
331      do t = 1,ktmx
332      start(4)=t
333      Status = nf_get_vara_real (id, idT, start, count, ts_tmp)
334      call handle_err(Status)
335      ts_169(1:imx,1:jmx,1:kmx,t) = ts_tmp(1:imx,1:jmx,1:kmx)
336      enddo
337
338
339      c There is no need to interpolate temperature since this variable
340      c is available at them RHO points.
341
342      c-----
343      c      Obtain starting and ending date of the data
344      c-----
345      c MEDSLIK_II input files are hour files. These files' names have the
346      c following structure: nameYMMDDHH, where name is a 4 digits
347      c description of the region where the data comes from.
348      c The main target of this work is to adapt the ROMS files so MEDSLIK_II
349      c can process them. Therefore, it is necessary to create these hour
350      c files and give them a name that follows the structure showed above.
351      c ROMS data, unlike MFS data, start at 00:00. The netcdf file contains
352      c a string (scrum_time) which stores the time since initialization.
353      c This variable will be used to obtain: initial date, final date and
354      c number of days.
355      c-----
356      c Extract scrum_time (st)
357
358      start_st(1) = 1
359      start_st(2) = 1
360

```



```

361      count_st(1) = ktmx
362      count_st(2) = 1
363
364      Status = nf_get_vara_int (id, idst, start_st, count_st, st)
365      call handle_err(Status)
366
367  c Starting month and day of the data
368
369      im=st(1,1)/86400
370
371      im1=im-31
372      im2=im-31-28
373      im3=im-31-28-31
374      im4=im-31-28-31-30
375      im5=im-31-28-31-30-31
376      im6=im-31-28-31-30-31-30
377      im7=im-31-28-31-30-31-30-31
378      im8=im-31-28-31-30-31-30-31-31
379      im9=im-31-28-31-30-31-30-31-31-30
380      im10=im-31-28-31-30-31-30-31-31-30-31
381      im11=im-31-28-31-30-31-30-31-31-30-31-30
382      im12=im-31-28-31-30-31-30-31-31-30-31-30-31
383
384      if (im1.le.0) then
385      month=1
386      day=im1+31
387      else if (im2.le.0) then
388      month=2
389      day=im2+28
390      else if (im3.le.0) then
391      month=3
392      day=im3+31
393      else if (im4.le.0) then
394      month=4
395      day=im4+30
396      else if (im5.le.0) then
397      month=5
398      day=im5+31
399      else if (im6.le.0) then
400      month=6
401      day=im6+30
402      else if (im7.le.0) then
403      month=7
404      day=im7+31
405      else if (im8.le.0) then
406      month=8
407      day=im8+31
408      else if (im9.le.0) then
409      month=9
410      day=im9+30
411      else if (im10.le.0) then
412      month=10
413      day=im10+31
414      else if (im11.le.0) then
415      month=11
416      day=im11+30
417      else if (im12.le.0) then
418      month=12
419      day=im12+31
420      else
421      print *, 'There is an error with the scrum time string'
422      endif
423
424  c Variable with the starting day of the data (YYMMDD)
425
426      write (monthc,'(i2)') month
427      write (dayc,'(i2)') day
428
429      if (month.lt. 10) then
430      if (day.lt. 10) then
431      Startd='150'//monthc(2:2)//'0'//dayc(2:2)
432      else

```

```

433      Startd='150'//monthc(2:2)//dayc(1:2)
434      endif
435      else
436      if (day .lt. 10) then
437      Startd='15'//monthc(1:2)//'0'//dayc(2:2)
438      else
439      Startd='15'//monthc(1:2)//dayc(1:2)
440      endif
441      endif
442
443  c Finishing month and day of the data
444
445      fm=st(169,1)/86400
446
447      fm1=fm-31
448      fm2=fm-31-28
449      fm3=fm-31-28-31
450      fm4=fm-31-28-31-30
451      fm5=fm-31-28-31-30-31
452      fm6=fm-31-28-31-30-31-30
453      fm7=fm-31-28-31-30-31-30-31
454      fm8=fm-31-28-31-30-31-30-31-31
455      fm9=fm-31-28-31-30-31-30-31-31-30
456      fm10=fm-31-28-31-30-31-30-31-31-30-31
457      fm11=fm-31-28-31-30-31-30-31-31-30-31-30
458      fm12=fm-31-28-31-30-31-30-31-31-30-31-30-31
459
460      if (fm1.le.0) then
461      fmonth=1
462      fday=fm1+31
463      else if (fm2.le.0) then
464      fmonth=2
465      fday=fm2+28
466      else if (fm3.le.0) then
467      fmonth=3
468      fday=fm3+31
469      else if (fm4.le.0) then
470      fmonth=4
471      fday=fm4+30
472      else if (fm5.le.0) then
473      fmonth=5
474      fday=fm5+31
475      else if (fm6.le.0) then
476      fmonth=6
477      fday=fm6+30
478      else if (fm7.le.0) then
479      fmonth=7
480      fday=fm7+31
481      else if (fm8.le.0) then
482      fmonth=8
483      fday=fm8+31
484      else if (fm9.le.0) then
485      fmonth=9
486      fday=fm9+30
487      else if (fm10.le.0) then
488      fmonth=10
489      fday=fm10+31
490      else if (fm11.le.0) then
491      fmonth=11
492      fday=fm11+30
493      else if (fm12.le.0) then
494      fmonth=12
495      fday=fm12+31
496      else
497      print *, 'There is an error with the scrum time string'
498      endif
499
500  c Duration data (in days). Addition of one since the last data is the
501  c one of the following day at 00:00
502
503      dur=(ktmx/24)+1
504

```

```

505 c      if (fmonth.eq.month) then
506 c      datadays=fday-day+1
507 c      else if (month.eq.1).or.(month.eq.3).or.(month.eq.5).or.
508 c      &      (month.eq.7).or.(month.eq.8).or.(month.eq.10).or.
509 c      &      (month.eq.12) then
510 c      datadays=(31-day)+fday+1
511 c      else if (month.eq.2)
512 c      datadays=(28-day)+fday+1
513 c      else
514 c      datadays=(30-day)+fday+1
515 c      endif
516
517 c-----
518 c      Create hourly files (romsYYMMDDHH)
519 c-----
520 c Now hourly files need to be created. Their names will follow the
521 c structure described below. Two loops are necessary: one for each day
522 c and one for each hour.
523 c
524
525      do d=1,dur
526      60  do t=0,23
527
528 c the day of the data needs to be updated. Currently, this program only
529 c performs simulations during the same month.
530
531      dayS=day+d-1
532
533      write (dia,'(i2)') dayS
534
535 c the hour needs to be converted into a character so it can be used to
536 c to define the file's name
537
538      write (hour,'(i2)') t
539
540      if (t.lt.10) then
541      if (dayS.lt.10) then
542      prdate = '0'//dia(2:2)//' '//Startd(3:4)//' '//Startd(1:2)//
543 &      ' '//'0'//hour(2:2)//':00'
544      else
545      prdate =dia(1:2)//' '//Startd(3:4)//' '//Startd(1:2)//
546 &      ' '//'0'//hour(2:2)//':00'
547      endif
548      else
549      if (dayS.lt.10) then
550      prdate = '0'//dia(2:2)//' '//Startd(3:4)//' '//Startd(1:2)//
551 &      ' '//'hour//':00'
552      else
553      prdate = dia(1:2)//' '//Startd(3:4)//' '//Startd(1:2)//
554 &      ' '//'hour//':00'
555      endif
556      endif
557
558      write(6,*) 'Writing medslk file for date '//prdate
559      write(99,*) 'Writing medslk file for date '//prdate
560
561      if (t.lt.10) then
562      outfile='fcst_data/ROMS/'//'roms'//Startd(1:2)//Startd(3:4)//
563 &      dia//'0'//hour(2:2)//'.opa'
564      else
565      outfile='fcst_data/ROMS/'//'roms'//Startd(1:2)//Startd(3:4)//
566 &      dia//hour//'.opa'
567      endif
568
569      inquire(file = outfile, EXIST = ex)
570      if(ex) then
571      open(20,file = outfile)
572      read(20,*) empty
573      read(20,*) empty
574      read(20,'(4f9.5,2i5)') blon1,blon2,blat1,blat2,imax1,jmax1
575      if(blon1.eq.alon1.and.blon2.eq.alon2.and.blat1.eq.alat1.and.
576 &      blat2.eq.alat2.and.imax1.eq.imax.and.jmax1.eq.jmax) then

```

One thing to take into c...
the hour 24 belongs to t...

```

577         write(6,*) outfile//' already exists for this subregion'
578         go to 60
579     endif
580     close(20)
581 endif
582
583 c-----
584 c   read OPA data files
585 c-----
586 c Since hour unique file has ktmx hours, when defining the hour files
587 c it is necessary to define a criteria so when the loop overpasses the
588 c first day, it continues through the ktmx hours.
589
590     if (d.eq.1) then
591         u(1:imx,1:jmx,1:kmx) = u_169(1:imx,1:jmx,1:kmx,t+1)
592         v(1:imx,1:jmx,1:kmx) = v_169(1:imx,1:jmx,1:kmx,t+1)
593         ts(1:imx,1:jmx,1:kmx) = ts_169(1:imx,1:jmx,1:kmx,t+1)
594     else if (d.lt.dur) then
595 c Definition of a variable that allows to continue further away hour 23
596         s=(d-1)*24+t+1
597         u(1:imx,1:jmx,1:kmx) = u_169(1:imx,1:jmx,1:kmx,s)
598         v(1:imx,1:jmx,1:kmx) = v_169(1:imx,1:jmx,1:kmx,s)
599         ts(1:imx,1:jmx,1:kmx) = ts_169(1:imx,1:jmx,1:kmx,s)
600     else
601         u(1:imx,1:jmx,1:kmx) = u_169(1:imx,1:jmx,1:kmx,ktmx)
602         v(1:imx,1:jmx,1:kmx) = v_169(1:imx,1:jmx,1:kmx,ktmx)
603         ts(1:imx,1:jmx,1:kmx) = ts_169(1:imx,1:jmx,1:kmx,ktmx)
604     endif
605
606 c-----
607 c   mask & nwp
608 c-----
609 c The ROMS file provides the mask on RH0-points. Therefore, it is not
610 c necessary to evaluate the values of u, v or ts since it is already
611 c know where are there water points.
612 c Extraction of the variable which stores the mask
613
614     start_mask(1) = 1
615     start_mask(2) = 1
616
617     count_mask(1) = imx
618     count_mask(2) = jmx
619
620     Status = nf_get_vara_int (id, idmask_rho, start_mask,
621 &     count_mask, mask)
622     call handle_err(Status)
623     print*, 'nnn', maxval(mask)
624     nwp = 0
625     do i=1,imx
626     do j=1,jmx
627         if(mask(i,j).eq.1) then
628             nwp = nwp + 1
629         endif
630     enddo
631     enddo
632
633     write(99,*) 'nwp = ',nwp
634     write(99,*) 'mask: '
635     do j=j_last,j_first,-1
636         write(99,'(30i1)') (mask(i,j),i=i_first,i_last)
637     enddo
638
639     write(99,*) 'ts: '
640     do j=j_last,j_first,-1
641         write(99,*) (ts(i,j),i=i_first,i_last)
642     enddo
643
644     i1 = i_first-2
645     i2 = i_last+2
646     j1 = j_first-2
647     j2 = j_last+2

```

```

649 c      if(i1.lt.1) i1 = 1
650 c      if(i2.gt.imx) i2 = imx
651 c      if(j1.lt.1) j1 = 1
652 c      if(j2.gt.jmx) j2 = jmx
653
654
655 c      call extrap3d(ts, i1, i2, j1, j2, imx, jmx, kmx)
656 c      call extrap3d(u, i1, i2, j1, j2, imx, jmx, kmx)
657 c      call extrap3d(v, i1, i2, j1, j2, imx, jmx, kmx)
658
659 c      write(99,*) 'ts after extrapolation: '
660 c      do j=j_last,j_first,-1
661 c          write(99,*) '(ts(i,j),i=i_first,i_last)
662 c      enddo
663
664 c      do i=i_first,i_last
665 c      do j=j_first,j_last
666 c          if(msk(i,j).eq.1) then
667 c              do k=1,kmx
668 c                  if(i.lt.imx) u(i,j,k) = (u(i,j,k) + u(i+1,j,k)) / 2.
669 c                  if(j.lt.jmx) v(i,j,k) = (v(i,j,k) + v(i,j+1,k)) / 2.
670 c              enddo
671 c          endif
672 c      enddo
673 c      enddo
674 c      enddo
675
676 c-----
677 c      write medslk files
678 c-----
679
680      open(20,file = outfile)
681      write(20,*) 'ROMS forecast data for '//prdate
682      write(20,*) 'Subregion of the Mediterranean with limits:'
683      write(20,'(4f9.5,2i5,''   Geog. limits'')')
684      &      alon1,alon2,alat1,alat2,imax,jmax
685      write(20,'(i6,''   0.0'')') nwp
686      heads = '      lat      lon      SST      '//
687      &      'u_srf      v_srf      u_10m      v_10m'//
688      &      '      u_30m      v_30m      u_120m      v_120m'
689      write(20,'(a150)') heads
690
691 c MEDSLIK_II uses as inputs the currents at the following depths: 10,
692 c 30 and 120 meters. Therefore, it is necessary to transform the S
693 c coordinates into z coordinates. The ocean_his file has all the
694 c parameters needed to obtain z(imx,jmx,kmx):
695
696      sc_r(1)=-0.95
697      sc_r(2)=-0.85
698      sc_r(3)=-0.75
699      sc_r(4)=-0.65
700      sc_r(5)=-0.55
701      sc_r(6)=-0.45
702      sc_r(7)=-0.35
703      sc_r(8)=-0.25
704      sc_r(9)=-0.15
705      sc_r(10)=-0.05
706
707      cs_r(1)=-0.972
708      cs_r(2)=-0.930
709      cs_r(3)=-0.882
710      cs_r(4)=-0.786
711      cs_r(5)=-0.588
712      cs_r(6)=-0.322
713      cs_r(7)=-0.128
714      cs_r(8)=-0.0417
715      cs_r(9)=-0.0116
716      cs_r(10)=-0.00198
717
718
719      start_h(1) = 1
720      start_h(2) = 1

```

```

721          count_h(1) = imx
722          count_h(2) = jmx
723
724
725
726          Status = nf_get_vara_real (id, idh, start_h,
727      &          count_h, h)
728          call handle_err(Status)
729
730
731      do i=i_first,i_last
732      do j=j_first,j_last
733          if(mask(i,j).eq.1) then
734
735              blon = oplon(i)
736              blat = oplat(j)
737              sst = ts(i,j,kmx)
738
739              us = u(i,j,kmx)
740              vs = v(i,j,kmx)
741
742
743              do l=1,imx
744              do m=1,jmx
745              do n=1,kmx
746                  z(l,m,n)=((hc*sc_r(n)+h(l,m)*cs_r(n))*h(l,m))/(hc+h(l,m))
747              enddo
748              enddo
749              enddo
750
751
752              if (z(i,j,1).ge. -10) then
753                  u10=u(i,j,1)
754                  v10=v(i,j,1)
755              else
756                  do k=1,kmx
757                      if (z(i,j,k+1).gt. -10) then
758                          u10=(u(i,j,k)+u(i,j,k+1))/2
759                          v10=(v(i,j,k)+v(i,j,k+1))/2
760                      exit
761                  endif
762              enddo
763              endif
764
765              if (z(i,j,1).ge. -30) then
766                  u10=u(i,j,1)
767                  v10=v(i,j,1)
768              else
769                  do k=1,kmx
770                      if (z(i,j,k+1).gt. -30) then
771                          u30=(u(i,j,k)+u(i,j,k+1))/2
772                          v30=(v(i,j,k)+v(i,j,k+1))/2
773                      exit
774                  endif
775              enddo
776              endif
777
778              if (z(i,j,1).ge. -120) then
779                  u10=u(i,j,1)
780                  v10=v(i,j,1)
781              else
782                  do k=1,kmx
783                      if (z(i,j,k+1).gt. -120) then
784                          u120=(u(i,j,k)+u(i,j,k+1))/2
785                          v120=(v(i,j,k)+v(i,j,k+1))/2
786                      exit
787                  endif
788              enddo
789              endif
790
791          write(20,'(13f11.4)') blat,blon,sst,us,vs,
792      &          u10,v10,u30,v30,u120,v120

```

```
793
794         endif
795     enddo
796 enddo
797 enddo
798 enddo
799 close(20)
800
801 return
802 end
803
804
805 C*****
806 C*****
807 C*****
808     SUBROUTINE HANDLE_ERR(Status)
809     include 'netcdf.inc'
810 c     include '/usr/local/include/netcdf.inc'
811     INTEGER Status
812     IF (Status .NE. NF_NOERR) THEN
813         PRINT *, NF_STRERROR(Status)
814         STOP 'Stopped'
815     ENDIF
816     END
```